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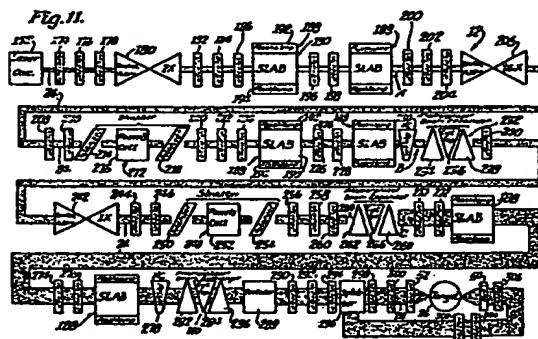
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(54) X-ray lithography system.

(57) An x-ray lithography system is disclosed in which x-rays are generated by directing a high energy laser beam against a metal target to form an x-ray emitting plasma. The x-rays from the plasma are then directed through a mask towards a resist covered wafer to cause a patterned exposure on the wafer resist coating. The mask, the portion of the target which the laser beam strikes and the portion of the wafer to be exposed are all within an evacuated chamber. The laser, prior to entering the chamber, is split into two separate beams, each of which are focused and directed through a window in the side of the chamber towards the same spot on the target. Apparatus, including an air bearing, seal and positioner, is provided to move the target at periodic intervals. Similar apparatus is provided to move the wafer from exposure section to exposure section. The laser beam system includes a face pumped laser beam amplifier and unidirectional beam expanders to allow the maximum energy to be transferred to the laser beam by the amplifier. A series of two or more laser pulses are provided in order to maximize the energy obtained from the laser amplifier. A magnet and a membrane shield are also provided to prevent high energy particles and dust contaminants from the plasma from effecting the lithography process. A materials handling device is provided for moving wafers, targets and masks and an alignment system operating within the evacuated chamber,

positions of the wafer with respect to the mask prior to the exposure thereof.



Description

X-RAY LITHOGRAPHY SYSTEM

This invention relates to an x-ray lithography system and more particularly, to such a system in which x-rays are generated by a laser beam striking a target with sufficient power to create an x-ray emitting plasma.

5 Semiconductor chips have been made by a process called lithography for many years. Typically, an energy source provides ultraviolet light through a mask which causes a pattern to appear on a resist coated silicon wafer. The light not blocked by the mask exposes the resist on the wafer and either the exposed or unexposed resist can be etched away, leaving a pattern on the wafer which can be further processed by known techniques.

10 As the demands for denser and denser semiconductor chips occur, a limitation on the use of ultraviolet light has been found. This limitation is due, among other reasons, to the wavelength of the light and the ability to make optical systems with sufficient resolution. Both of these reasons result in a finite size of line, in the order of 1.0-1.5 microns, which can be placed on the chip. It has been known for several years that to break the density barrier of ultraviolet light photolithography processing, a different energy source must be used. One
15 type of energy source which has been widely suggested has been x-rays, which have a shorter wavelength than ultraviolet light and do not require sophisticated optical devices. X-ray lithography was first suggested by Smith, et al, in U.S. Patent No. 3,743,842 entitled Soft X-Ray Lithographic Apparatus and Process. Later, Nagel, et al, in U.S. Patent No. 4,184,078 suggested using a plasma emitting x-ray source to generate the x-rays. Of particular significance herein is the embodiment of Nagel et al in which a laser was focused on a metal target and caused the plasma to be created. Improvements to the basic Nagel technique have been made by the
20 assignee hereof in U.S. Patent Application Serial Nos. 669,440, 669,441 and 669,442, which relate to improvements in the x-ray generating source means.

In accordance with one aspect of this invention, there is provided a high energy laser beam generator including a laser beam oscillator for providing a narrow and low energy laser beam relative to the desired
25 output beam; a face pumped laser amplifier having a path for laser beam energy amplification of a first distance in one direction and a second distance in a perpendicular direction, said second distance being substantially greater than said first distance; first laser beam direction means for directing said laser beam generated by said oscillator through said amplifier along one part of said path characterized by second laser beam direction
30 means, including beam expander means for expanding the size of the beam to not greater than said first distance along one axis of said beam and to between said first and second distances along another axis, said second direction means further including means for redirecting said expanded laser beam through said amplifier along a second part of said path, not intersecting said first part of said path.

The said beam expander means may include an anamorphic beam expander.

35 The said second direction means may include second beam expander means to expand said beam exiting said amplifier path along said first axis to the same size as expanded along said other axis.

The said first beam expander means and the said second beam expander means may each include an anamorphic beam expander.

Alternatively, the said first beam expander means and the said second beam expander means may each include a plurality of triangular shaped prisms.

40 According to another aspect of the present invention there is provided a laser beam generator for generating a high power laser beam comprising a laser oscillator for providing an initial laser beam; a face pumped laser beam amplifier including a glass slab having two main faces into which optical energy is pumped and a cross sectional area between said two main faces of a certain height separating said two main faces and a certain width perpendicular to and greater than said certain height; first directing means for directing said
45 laser beam provided from said oscillator through a first path between the main faces of said slab to obtain a first amplified laser beam characterized by means for expanding said first amplified laser beam in a direction oriented with said height to a dimension less than said height and in a direction oriented with said width to a dimension greater than said height and less than said width to obtain an expanded laser beam; and second directing means for directing said expanded laser beam through a second path, remote from said first path,
50 between the main faces of said slab to obtain said high power laser beam.

The said first directing means may include shutter means.

The said second directing means may also include shutter means.

55 The said generator may further include second means for expanding said expanded laser beam in said direction oriented with said height to a dimension greater than said height to obtain said high power laser beam.

The said first mentioned means for expanding and said second means for expanding may each include anamorphic beam expanders.

60 The said first directing means may include first and second beam expanding means for expanding a laser beam applied thereto in a substantially symmetrical manner; means for providing said oscillator provided laser beam to said first expanding means to obtain a first expanded laser beam of a dimension less than said height; means for directing said first expanded laser beam through said slab along a first part of said first path to obtain an initial amplified laser beam; means for providing said initial amplified laser beam through said second beam expanding means to obtain a second expanded laser of a dimension substantially the same as said

height; and means for directing said second expanded laser beam through said slab along a second part, different from said first part, of said first path to obtain said first amplified laser beam.

The said first and second beam expanding means may include spatial filters.

The said first and second parts of said first path may be adjacent to one another and coextensive with the length of said slab.

The invention further comprises a method for generating a high power laser beam using a face pumped laser beam amplifier, including a glass slab having two main faces into which optical energy is pumped and a cross sectional area between said two main faces of a certain height separating said two main faces and a certain width perpendicular to and greater than said certain height, said method including the steps of generating an initial laser beam; directing said generated initial laser beam through a first path between the main faces of said slab to obtain an amplified laser beam; said method being characterized by the steps of expanding said amplified laser beam in a direction oriented with said height to a dimension less than said height and in a direction oriented with said width to a dimension greater than said height and less than said width to obtain an expanded laser beam; and directing said expanded laser beam through a second path, remote from said first path, between the main faces of said slab to obtain said high power laser beam.

The said step of directing said generated initial laser beam may include the step of symmetrically expanding said initial laser beam.

The said step of symmetrically expanding said initial laser beam may further include the step of directing said symmetrically expanded laser beam through a third path, different from said first and second paths, between the main faces of said slab.

The said step of directing said laser beam through said third path may include directing said laser beam through a spatial filter for symmetrically expanding said beam to a dimension substantially equal to said height.

The said step of directing said expanded laser beam may further include the step of expanding said laser beam obtained from said slab in a direction oriented with said height to be substantially the same as the dimension oriented in the direction associated with said width.

One preferred embodiment of the subject invention is hereafter described, with specific reference being made to the following Figures, in which:

Figure 1 shows a prospective view, partially in cut-away, of the x-ray lithography system of the subject invention;

Figure 2 shows a plan front view of the wafer processing and a portion of the x-ray source of the x-ray lithography system of the subject invention;

Figure 3 shows a more detailed side view, partially in cross section, of the x-ray source of the system of the subject invention;

Figure 4 shows a more detailed front view, partially in cross section, of the x-ray source of the subject invention;

Figures 5 and 5A show one type of interface between the x-ray emitting chamber and the wafer of the subject invention;

Figure 6 shows a drawing useful in understanding the operation of the subject matter shown in Figures 5 and 5A;

Figures 7 and 7A show an alternate embodiment of the interface between the x-ray generating chamber and the wafer;

Figure 8 shows a diagram of the target and associated target moving mechanism used in generating the x-ray emitting plasma;

Figure 9 shows a bottom view of the target moving mechanism used to interface the target and the vacuum chamber of the subject invention;

Figure 10 shows the laser system and path of the laser beam used in generating the x-ray emitting plasma;

Figure 11 is a schematic diagram representing the laser system of the subject invention;

Figure 12 shows the shape and position in the amplifier glass slab of the laser beam during various passes through the amplifier, as shown in Figure 11;

Figure 13 shows a three dimensional view of the component placement of the laser system shown in Figure 11;

Figures 14A, 14B and 14C represent respectively the top, front and side views of the view shown in Figure 13;

Figure 15 is an overall block diagram of the electrical control system of the subject invention;

Figure 16 shows the manner in which Figures 16A and 16B are placed together;

Figures 16A and 16B show a more detailed electrical system diagram of the subject invention;

Figures 17A and 17B show a flow diagram of the initiation procedure prior to utilizing the subject invention in production;

Figure 18 shows a flow diagram of the stand-by operation of the subject invention;

Figure 19 shows a flow diagram of the manner in which data is loaded into the computer of the subject invention;

Figure 20 shows a flow diagram of the manner in which the target may be loaded into the machine of the subject invention; and

Figure 21 shows the manner in which the masks may be loaded into the machine of the subject

invention.

Referring now to Figure 1, X-ray lithography (XRL) system 10 is shown. System 10 includes a laser system 12, a materials handling system 14, an x-ray generating system 16, a wafer handling system 18 and a control system 20. Laser system 12 includes of a high powered and high repetition rate laser oscillator and amplifying means, together with a plurality of filters, shutters and mirrors, to cause a pair of powerful laser beams to be directed into the x-ray generating system 16. The details of the laser system 12 are explained hereafter with respect to Figures 11-14.

The x-ray generating system 16 includes an evacuated chamber 22 into which is focused a pair of laser beams 24 and 24A from laser system 12. The beams 24 and 24A are directed to strike a target 26 interfaced with chamber 22, causing a plasma to result. As with any plasma, x-rays are emitted, which x-rays travel through the evacuated chamber 22, and through the x-ray transmissive parts of a mask positioned within the chamber, towards a silicon wafer on wafer handling system 18. The mask and a desired portion of the wafer are placed and maintained in proper position and alignment by the material handling system 14. Each of the systems 12, 14, 16 and 18 are controlled by the control system 20.

Referring now to Figure 1A, the material handling system 14 is shown and includes a robot 28 having an arm and platform mechanism 30. Robot 28 controls its arm and platform 30 to pick-up and move a member 32, such as a wafer, target or mask. A stack of members 32 to be moved may be loaded into XRL System 10 using an SMIF container 34, which is designed to maintain a purified air atmosphere therein to avoid contamination of the member 32 while being moved or loaded. XRL System 10 includes two receptacles to receive SMIF containers 34, one in the front, as seen in Figure 1, and the other on the side (not seen).

Robot 28 may be controlled to remove the members 32 inserted into system 10 using container 34 and to stack them in various positions 36. From the positions 36, robot 28 may later move an individual member 32 into proper position, which position is described in more detail hereafter. After a wafer is completely processed it may be returned to container 34 and when container 34 is full, it may be removed from system 10 and taken to the next processing station. Similarly, unused masks or used targets can be removed using robot 28.

Referring now to Figure 2, a plan view from the front of XRL System 10 is shown with the external panels removed so that the wafer handling system 18 and portions of the x-ray generating system 16 are seen. In Figure 2, laser system 12 rests on a granite slab 38. Slab 38, in turn, rests on a platform 40 which, rests on a second granite slab 42. While not seen in Figure 2, granite slab 42 is held by a support above the control system 20.

Both granite slabs 38 and 42 are designed to have very flat and uniform top surfaces. This is particularly necessary in the case of support 42 to enable wafer handling system 18 to properly operate and position the wafer being processed in proper alignment. Further, each of the granite slabs 38 and 42 are extremely heavy, and thus, prevent any vibrations from affecting the proper operation of system 10.

Granite slab 38 has a pair of vertical holes 44 and 46 positioned through the interior thereof to allow the two laser beams 24 and 24A from laser system 12 to be directed towards the x-ray generating system 16. Each of the two holes 46 are aligned with a mirror 48 and 50 respectively. Each of the mirrors 48 and 50, in turn, reflect the laser beams 24 and 24A towards focusing lenses 52 and 54 respectively, which focus the laser beams at a small point on the target 26 area. The details of this structure will be explained hereafter with respect to Figure 4.

After the laser beams 24 and 24A have been focused on target 26, the resulting plasma at target 26 generates x-rays 56 throughout chamber 22, some of which are directed towards wafer 58. A mask, positioned within chamber 22 between the plasma and wafer 58, causes a pattern of x-rays to strike wafer 58. This pattern exposes the resist layer covering wafer 58 so that wafer 58 can be further processed.

Wafer 58 is moved in discrete steps by wafer handling system 18. Wafer handling system 18 includes a chuck 60 which is moveable in the X, Y, Z and theta directions, so as to properly position wafer 58 at the desired place in alignment with the pattern of x-rays 56 from chamber 22. It is necessary that wafer 58 be very precisely positioned within a few tenths of a micron because the various steps used in processing wafer 56 require alignment to that accuracy. The wafer handling system 18 may be any conventional wafer stepper device, such as the one used in the Ultrastep 1000 Photolithography System described in more detail in U.S. Patent 4,444,492 in the name of Martin E. Lee, and entitled "Apparatus for Projecting a Series of Images onto Dies of a Semiconductor Wafer".

Referring now to Figures 3 and 4, X-ray generating system 16 is shown in more detail. More specifically, Figure 3 shows a side view, including the interior details of chamber 22, and Figure 4 shows a front view, including interior details of chamber 22. Laser beams 24 and 24A, applied from laser system 12 through openings 44 and 46, are deflected by mirrors 48 and 50 to pass through focusing lenses 52 and 54. In Figure 4, focusing lens 54 is shown in cut-away and consists of a plurality of focusing lenses 62...64. Laser beams 24 and 24A pass through focusing lens 52 and focusing lens 54 and are reflected by respective mirrors 66 and 68, positioned on the outside of chamber 22, through windows 70 and 72, respectively, towards target 26. Focusing lenses 52 and 54 and mirrors 66 and 68 are positioned such that when laser beams 24 and 24A are focused by lenses 52 and 54 and reflected by mirrors 66 and 68, they impinge upon a single small spot 74, which may be on the order of 50 to 100 microns in diameter, on target 26. Thus, the center-line distance from lenses 52 or 54, respectively, to spot 74 as reflected by mirrors 66 or 68, respectively, is equal to the focal lengths of lenses 52 or 54.

Chamber 22 is desirably an evacuated chamber having a pressure of less than a few Torr. The gas remaining within chamber 22 is preferably an inert gas, such as helium. In order to maintain the vacuum, as laser beams 24 and 24A enter into chamber 22, windows 70 and 72 are hermetically sealed with the sides of chamber 22. Target 26 is positioned at the top of chamber 22 to allow it to both be moved and to provide a vacuum seal, as described hereafter with respect to Figures 8 and 9. The bottom of chamber 22 is also hydrodynamically sealed and moveable across wafer 38 as described in more detail with respect to figures 5, 5A, 6, 7 and 7A. 5

As laser beams 24 and 24A are focused by lenses 52 and 54 and reflected by mirrors 66 and 68 towards a focal point spot 74, the temperature of target 26 increases to greater than a million degrees centigrade. Target 26 may be any conventional metal material, such as stainless steel, and when the laser beams 24 and 24A are focused at spot 74, a plasma is created which emits x-rays 56 throughout the entire evacuated inner portion of chamber 22. One manner in which the plasma is emitted is described in more detail in U.S. Patent Application Serial No. 669,441 in the name of James Forsyth and assigned to the assignee hereof. 10

When the plasma is generated, two types of contaminants are emitted from the plasma, in addition to the x-rays. The contaminants are dust particles, which result from the evaporating metal, and charged particles. A magnet 76 may be placed around the outside of container 22, as shown in Figure 3, or alternately, within container 22, and is poled to deflect the charged particles away from the critical area where the lithography processing is occurring. The positioning of magnet 76 should be out of the path of laser beams 24 and 24A and thus preferably will be outside of container 22. Much of the dust particles will fall harmlessly onto the structure supporting windows 70 and 72 out of the path of the x-rays 56 critical to the lithography process. The dust particles in the x-ray 56 path will be blocked by an x-ray transmissive membrane 77. Membrane 77 may be a silicon membrane, held by a conventional support, and means may also be provided to move, or remove, membrane 77 together with its support, in order to remove the dust particles collected thereon from the x-ray path. 15

In order to make XRL system 10 useful in production applications, it is desirable that target 26 have a life exceeding 4 to 8 hours. One technique for extending the life of the target has been previously described in U.S. Patent Application Serial No. 669,440 in the name of James M. Forsyth and assigned to the assignee hereof. In that Patent Application, targets in the shape of either a cassette held strip of metal or a metal drum shaped object were shown as being placed wholly within the evacuated portion of chamber 22. In XRL System 10, a plate, or disc shaped object is utilized as target 26. Laser beams 24 and 24A may be focused at separate and distinct points along a plurality of different tracks of the disc shaped target 26. Further, it may be desirable to increase the usage of the disc material by firing a plurality of different laser pulses into areas in which cavities have been predefined on target 26, such as been described in U.S. Patent Application Serial No. 669,440. Alternatively, a plurality of laser pulses may be fired into the target area for each exposure. 20

Target 26 may be held by a vacuum chuck 78, which is designed to be moved in both a circular and longitudinal direction over a plate 80, extending from the upper portion of chamber 22. The movement of chuck 78, and the held target 26, is under the control of a stepper motor 82 and a linear movement device 84. Linear movement device 84 may include a rotating screw which moves stepper motor 82 from the left to right, as seen in Figure 4. Stepper motor 82 has a shaft extending therefrom which can be rotated in response to commands from the control system 20 by precise amounts, thereby causing chuck 78, and target 26 held thereby, to rotate around the various tracks of target 26. As soon as a complete rotation has occurred for a particular track, linear movement device 84 may be engaged to move stepper motor 82 so that a rotation around another track occurs. After all of the tracks of target 26 are used, target 26 is replaced by a new metal plate. 25

The shaft from stepper motor 82 is coupled to a ferrofluidic coupler 86 having a stationary portion and a rotating portion. The stationary portion may have air pressure and air vacuum lines coupled to it, which, in turn, are coupled to the rotating portion of coupler 86. Air pressure and vacuum paths are then coupled through shaft 88 to control both a bellows device 90, used to raise or lower chuck 78, and a plurality of vacuum ports, used to hold target 26 in place, depending on whether air is applied or removed through the ferrofluidic coupler 86. When it is desired to replace target 26, bellows device 96 is raised, thereby raising chuck 78 so that the arm and platform 30 of robot 28 can remove the spent target 26 and replace it with a new target. 30

In order for a sufficient intensity of x-rays to be generated, the plasma created should be in the partially evacuated chamber 22. Thus, at least the surface of target 28 which the laser beams 24 and 24A strike must be in the partial vacuum. 35

The structure by which chuck 78 forms a vacuum seal for maintaining the partial vacuum in chamber 22 and also forms an air bearing for allowing movement of target 28, as well as allows target 26 to be properly positioned so that laser beams 24 and 24A can be focused at spot 74, will be described hereafter with respect to Figures 8 and 9. 40

The bottom of chamber 22 has an opening 92 therein into which a mask 94 is to be positioned. Mask 94 may be any conventional x-ray mask, such as a silicon membrane having a pattern of a heavy metal, such as gold, deposited thereon. The pattern portion contained on mask 94 should be in alignment with the opening 92 at the bottom of chamber 22. The remaining portion of mask 94 is a support for the silicon membrane and a plurality of inlet and outlet paths for vacuum and pressure to be connected to maintain the seal, provide an air bearing and properly position the mask with respect to wafer 58. The exact manner in which the seal, air bearing and positioning occurs will be described hereafter with respect to Figures 5, 5A, 6, 7 and 7A. 45

Positioned generally in the lower part of chamber 22 above mask 94, is the wafer alignment mechanism 96. Alignment mechanism 96 may be similar in concept to the alignment mechanism used to position and align 50

wafers in conventional photo- lithography techniques, such as those utilized in the Ultrastep 1000 stepper described in the aforementioned U.S. Patent 4,444,492. However, specific differences exist between the alignment mechanisms of x-ray lithography system 10 and the prior art, due, in part, to the requirement that the alignment techniques utilizes marks on mask 94 and mask 94 must be within the evacuated portion of chamber 22.

The alignment mechanism is best seen in Figure 3 and includes a pair of optical emitters and detector units 98 and 100. Light is provided from and reflected light is provided back to each of emitter and detector units 98 and 100 through a pair of moveable chambers 102 and 104. Each of the chambers 102 and 104 is shown in the closed position in Figure 3, which occurs when wafer 58 is being moved by wafer handling system 18. Light beams 106 and 108, provided from mercury arc lamps in the emitter portion of emitter and detector units 98 and 100, travels through chambers 102 and 104, which function as a microscope, and is reflected by mirrors 110 and 112 towards wafer 58. As long as a predefined optical alignment mark is not in the path of the light from beams 106 and 108, light is reflected back along the same path towards mirrors 110 and 112. A small hole in the mirrors 110 and 112, coupled by a fiber optic cable to the detector part of emitter and detector units 98 and 100, provides a path for the reflected light to be detected. Whenever the alignment markers appearing on wafer 58 are moved into the path of light beams 106 and 108, the light is scattered away from the original path and the scattered light is detected by units 98 and 100 to indicate that the wafer has moved to a certain aligned position.

As soon as wafer 58 is properly positioned by the emitter and detector units 98 and 100, electrical signals are provided to control system 20, which, in turn, causes wafer handling system 18 to stop moving wafer 58. At the same time, signals are provided to cause moveable chambers 102 and 104 to move out of the path of the x-rays 56 from spot 74 through opening 92. The two moveable chambers 102 and 104 are each coupled to chamber 22 by bellows connectors 114 and 116 which allow the partial vacuum within chamber 22 to be maintained regardless of the position of chambers 102 and 104. The light beams 106 and 108 are applied through hermetically sealed windows 118 and 120 at the ends of chambers 102 and 104. When moveable chambers 102 and 104 are moved out of the path of the x-rays 56, the laser beams 24 and 24A can be provided and focused on spot 74 to cause the x-rays to be generated and be applied through the evacuated interior of chamber 22 towards mask 94 to cause a pattern of x-rays to be provided to wafer 58. Thereafter, the bellows connectors 114 and 116 are controlled to move chambers back to the position shown in Figure 3 and wafer 58 is moved and aligned in the next position in the manner previously described.

Referring now to Figures 5, 5A, 6, 7 and 7A, the air bearing, seal and mask to wafer gap monitoring mechanism between the bottom of mask 94 and the resist layered surface of wafer 58 will now be described. One embodiment of this structure is shown in Figures 5 and 5A and includes a mask support ring 122 having a silicon membrane 124 attached to the bottom side thereof. The pattern 125 on mask 94 is fabricated on the portion of silicon membrane which extends over an opening 126 of support ring 122. As seen in Figure 4 and described herein in more detail, support ring 122 may be inserted in the bottom of chamber 122 in alignment with certain inlet and outlet paths through which gas may be pumped or evacuated.

The inlet and outlet paths from chamber 22 extend into mask support ring 122 and include vacuum paths 128 and 130, which are the inner two paths from the center of support ring 122, as seen in Figures 5 and 5A, a helium pressure path 132 and an air, or nitrogen, pressure path 134. There is a significantly longer distance between paths 132 and 134 than between paths 128 and 130 or 130 and 132. A vacuum pump may be attached to the exit side of paths 128 and 130 near the bottom of chamber 22 and helium may be pumped through path 132 and air, or nitrogen, may be pumped through path 134 from the inlets to those paths near the bottom of chamber 22.

The bottom of mask support ring 122 and silicon membrane 124 have a plurality of rings 138, 140, 142 and 144 therein. Ring 138 is coupled to path 128 and ring 140 is coupled to path 130. Thus, any gas which is in the area of rings 138 or 140 is evacuated through paths 128 and 130. In the same manner, ring 142 is coupled to path 132 and ring 144, which is substantially wider than the other rings 136, 138 and 140, is coupled to path 134.

Three prealignment notches 146 are positioned on the side of mask support ring 122 and, together with corresponding solenoids 147, are used to prealign mask support ring 122 within the area of the bottom of chamber 22. This is done during the time robot 28, shown in Figure 1A, moves a mask 94, which includes mask support ring 122 and silicon membrane 124, from the stack of masks into the position shown in Figure 4. Once mask 94 is positioned by the arms of solenoids 147 extending into notches 146, mask 94 is held in position by a vacuum path 149.

Referring now to Figure 6, the manner in which mask support ring 122 and silicon membrane 124 function to provide the vacuum seal, air bearing and mask to wafer vertical gap positioner will now be described. First, however, it should be understood that the interior portion of chamber 22 is at a relative pressure of, for example, less than a few Torr, whereas, the outside of chamber 22 is at normal atmospheric pressure of approximately 760 Torr. Further, the distance between the pattern portion 125 of membrane 124 and the top of wafer 58 must be critically controlled to be approximately 30 microns. In addition, wafer 58 must be readily moveable with respect to mask support ring 122 and silicon membrane 124 without disturbing the pressure within the evacuated inner portion of chamber 22.

By providing a vacuum pump connection to paths 128 and 130 and by connecting path 128 into the interior of chamber 22 by path 136, the low pressure vacuum within chamber 22 is maintained, as indicated by the lines 148 and 150 in Figure 6. The use of two or more channels, such as paths 128 and 130, allows the pressure

within chamber 22 to be maintained at a relatively low value, such as less than a few Torr. Such a vacuum seal has been previously utilized in the Varian Microseal system wafer transport and handling mechanism to maintain a vacuum within an electron beam chamber. However, if one could utilize this structure to additionally maintain the distance between membrane 124 and the top of wafer 58 at a precise value as well as allow relative movement on both sides of the seal, additional other structure could be eliminated.

To obtain these added features, paths 132 and 134 are utilized. Helium is applied through path 132 and air, or nitrogen, is applied through path 134. By adjusting the pressure of the helium and the air, or nitrogen, applied through paths 132 and 134, a high pressure can build up at point 152, shown in Figure 6. This high pressure at point 152, in conjunction with the relatively low evacuated pressure at other portions, such as point 154 beneath membrane 124 in the critical areas where the exposure takes place, maintains the distance between membrane 124 and the top of wafer 58 at a precise distance. This distance can be varied by varying the pressure of the helium and air passing through paths 132 and 134. Further, the high pressure at point 152 acts as an air bearing, allowing friction free movement between membrane 124 and wafer 58. Despite such movement, the evacuation at openings 128 and 130 still maintains the vacuum within chamber 22 and on both sides of the membrane 124. Further, the constant evacuated pressure on both sides of membrane 124 prevents warping of membrane 124 from occurring.

Referring now to Figures 7 and 7A, an alternate embodiment of the concept described with respect to Figures 5, 5A and 6 is shown. In this instance, ring 144 of Figure 5 is replaced by a series of small holes 156 through the membrane 124. In addition, three gap sensors 158 are included to sense the gap distance between membrane 124 and wafer 58. Such gap sensors may be of the type utilized in the Ultrastep 1000 photolithography system to seek identical back pressure for each sensor to achieve a parallel alignment between membrane 124 and wafer 58.

Referring now to Figures 8 and 9, the vacuum seal and air bearing between the chuck 78 holding target 26 and plate 80 at the top of chamber 22 is shown. Target 26 is held firmly against the recessed center of chuck 78 by a plurality of vacuum supports 160, each of which has an evacuation port 162 at the center thereof connected to a vacuum pump (not shown).

When it is desired that target 26 be moved by motor 82 and/or linear movement device 84, the nonrecessed peripheral edge of chuck 78 is to glide over plate 80. An air bearing and seal, similar to that described with respect to Figure 6, in the peripheral edge of chuck 78 prevents loss of the vacuum from within chamber 22 and allows friction free movement of chuck 78 with respect to plate 80. In this instance, however, only a single vacuum path 164 and a single air path 166 are utilized. Each of the paths 164 and 166 are connected to rings 168 and 170 at the bottom of chuck 78. The air pressure into path 166 and the vacuum from path 164 causes the air bearing and seal, described with respect to Figure 6. In practice it may be desirable to utilize a plurality of vacuum paths 164 and rings 168 and a plurality of pressure paths 166 and rings 170, such as shown in Figure 6, in order to obtain the vacuum and adjust the distance in a more accurate fashion.

Referring now to Figures 10, 11, 12, 13 and 14A through 14C, the laser system 12 will now be described. Figure 10 shows the manner in which a single laser beam 24 is generated by laser system 12, subsequently passed through a beam splitter to form the dual beams 24 and 24A that are passed through the two holes 44 and 46, reflected by the two mirrors 48 and 50 through focusing lenses 52 and 54 and reflected by the two mirrors 58 and 60 into the chamber 22. The reason that two beams 24 and 24A are utilized is that the power required of the laser to create the plasma is so great that handling the beam with conventional mirror and focusing equipment would result in short component lifetimes, even with special dielectric coatings. By reducing the intensity in each of the two laser beams 24 and 24A applied into chamber 22 by approximately 50 percent, conventional component materials may be used with a normal useful life for those materials. This is particularly important because some of the component materials through which the laser beam passes can become very expensive to replace.

Figure 11 shows schematically the manner in which the dual laser beams 24 and 24A are generated and Figure 12 shows the shape and position of the laser beam 24 during each of its three passes through the laser amplifier. Figure 13 shows a three dimensional representation of the positioning of each of the major components to be described in Figure 11 and Figures 14A, 14B and 14C show respectively, the top, front and side views of the three dimensional structure shown in Figure 13. Hereafter, the individual components will be described in detail with respect to Figure 11, with reference to Figure 12 on occasion. Numerical designations of the components have been added to Figures 13 and 14A through 14C, but no specific description is given.

In Figure 11, a conventional laser oscillator 172 provides a narrow laser beam 24 through an aperture 174. The beam 24 is reflected by mirrors 176 and 178 through a spatial filter 180, which increases the size of the beam 24 by approximately two times. It should be noted that the major components described in Figure 11 have been marked with numerical designations in Figures 13 and 14A, 14B and 14C. However, the minor components, such as mirrors 176 and 178 and aperture 184, have been deleted from Figures 13, 14A, 14B and 14C to increase the clarity of those Figures.

The laser beam 24 from spatial filter 180 is again reflected by mirrors 182, 184 and 186 and provided through the laser beam amplifier 188. Amplifier 188 consists of a neodymium doped slab of glass, surrounded by a pair of flash lamp elements 192 and 194. The laser amplifier 188 is similar to the type described in U.S. Patent 3,633,126 in the name of William S. Martin et al and entitled "Multiple Internal Reflection Face Pumped Laser". Generally, the beam 24 incident to the laser amplifier 188 picks up the energy stored in the glass resulting from energizing the flashlamps 192 and 194. Thus, the laser beam 24 at the output of laser amplifier 188 is

significantly more powerful than the laser beam 24 incident thereto.

Next, the laser beam 24 is reflected by mirrors 196 and 198 back through laser amplifier 188 along the same path as previously traveled. When the laser beam 24 exits amplifier 188 on the second pass, it is shaped and positioned as shown by beam A, in Figure 12.

5 Next, the laser beam 24 is directed by mirrors 200, 202 and 204 to enter spatial filter 206, which magnifies the size of the beam 24 by a factor of approximately 1.6 in all directions. Thereafter, the laser beam 24 is reflected by mirrors 208 and 210 through a shutter assembly 212. Shutter assembly 212 consists of a linear polarizer 214, Pockels cell 216 and a second linear polarizer 218, which is rotated 90 degrees with respect to the first polarizer 214. Pockels cell 216 is controlled by signals from the control system 20 and, as is well known, changes the polarization of the beam incident thereto by 90 degrees when enabled. Thus, when the Pockels cell 216 is enabled, beam 24 continues to pass through shutter 212 and when Pockels cell 216 is not enabled laser beam 24 is blocked by polarizer 218. It should be noted that shutter 212 operates the same in both directions, so that any reflected beam would be blocked just as the beam originated within oscillator 172 is blocked when Pockels cell 216 was not enabled. Thus, the enable signal for Pockels cell 216 from control system 20 should be a very short pulse, timed to only allow the primary beam 24 pulse or pulses generated by oscillator 172 to pass, and to block any reflected beams.

Next, mirrors 220, 222 and 224 direct the laser beam 24 through amplifier 188 a second time and mirrors 226 and 228 direct the then amplified beam 24 back along the same path through amplifier 188. Upon exiting amplifier 188 for the second time, the laser beam 24 is positioned and shaped as beam B shown in Figure 12. It should be noted that beam B is approximately 1.6 times as large as beam A due to the multiplication by spatial filter 206. Further, the mirrors 222 and 224 direct the laser beam 24, during the second pass through amplifier 188, along a different path through glass slab 190 than occurred during the first pass.

The output from amplifier 188 is redirected by a prism 230 into an anamorphic beam expander 232. The anamorphic beam expander 232 consists of three prisms, triangular shaped in one plane and rectangularly shaped in a second plane perpendicular to the first mentioned plane. Each of the three prisms act to expand the beam only in one direction. In this case, the three prisms 234, 236 and 238 of beam expander 232 expand the laser beam only in the X direction.

Thereafter, the beam 24 from beam expander 232 is directed by a mirror 240 through a spatial filter 242, which does not change the size of the beam 24. Next, the beam 24 is directed by mirrors 244 and 246 through a second shutter 248, which includes polarizers 250, Pockels cell 252 and polarizer 254. Shutter 248 operates in the same manner as previously described with respect to shutter 212. In order to stop all reflected beams, it is desirable to use a pair of shutters within the system, since some light leaks through the shutters.

Next, the laser beam 24 is directed by mirrors 256, 258 and 260 through a second anamorphic beam expander 262, which includes prisms 264, 266 and 268. Expander 262 again expands the beam 24 only in the X direction. From beam expander 262, the laser beam 24 is directed by mirrors 270 and 272 through amplifier 188 for a third pass and mirrors 274 and 276 redirect the beam 24 back through amplifier 188. During this third pass, the laser beam 24 appears as beam C in Figure 12, which shows it has been greatly expanded in the X direction, but remains generally the same size in the Y direction as it was when it had the shape of beam B. Further, the mirrors position beam C at a different location along the slab 190 so that the beam can pick up the energy in slab 190 in that position. It should be noted that the spatial filters 180, 206 and 242, anamorphic beam expanders 232 and 262 and the cross sectional size of slab 190 are all selected so that laser beam 24 is expanded to not greater than the Y dimension size of slab 190 in the Y direction, but may be expanded to significantly greater than the Y dimension size in the X direction. This type of expansion allows laser beam 24 to absorb as much of the slab 190 stored energy as possible.

45 Upon leaving amplifier 188, after the third pass therethrough, laser beam 24 is directed by prism 278 through a third anamorphic beam expander 280, consisting of prisms 282, 284 and 286, which expand beam 24 in the Y direction so that it again becomes of generally circular cross section. From expander 280, the beam 24 is passed through isolator 288 and directed by mirrors 290, 292 and 294 to a beam splitter 296. Beam splitter 296 splits the incident laser beam 24 into two separate and generally equal intensity beams 24 and 24A. One of the beams 24 from beam splitter 296 is directed by mirrors 298 and 300 through opening 44 to lens 52 and on to target 26, as previously described. The second beam 24A from beam splitter 296 is directed by mirrors 302, 304 and 306 through lens 54 towards target 26 utilizing opening 46 in the granite slab 38.

The operation of laser system 12 is designed according to the following considerations. The production of intense pulses of soft x-rays by means of focusing high peak power laser pulses onto suitable targets has an important commercial application in the field of soft x-ray lithography. As described in the aforementioned U.S. Patent 4,184,078, a pulsed neodymium laser is suitable for use in this application. When a neodymium laser is to be configured to generate a sufficiently intense pulse for such an application, one or more stages of amplification are normally employed in conjunction with a pulsed, typically Q-switched, neodymium oscillator. The degree of amplification of such pulses which can be conveniently achieved in compact systems is typically limited by the ability of optical surfaces employed subsequent to the amplifier system to withstand the intensity of the laser pulse without suffering permanent damage. This is especially true when multilayer dielectric optical coatings are employed to improve the efficiency of laser beam transport. By limiting the degree of amplification to that permitted by damage considerations, the amplifier medium typically exhibits significant further amplification potential after the passage of the laser pulse. This remaining amplification represents unused laser pump energy which is lost after a short interval of time due to radiative decay of the excited laser state in

neodymium. In other words, this unused available energy corresponds to reduced system efficiency.

One approach to minimize this problem is to expand the cross sectional area of the laser beam immediately after amplification by the use of lenses and/or prisms. Such an approach is used in the NOVA system, a large pulsed neodymium system installed at the Lawrence Livermore National Laboratory, Livermore, California, to enable the extraction of the highest possible fraction of amplifier stored energy in the passage of a single laser pulse. Such an approach creates a significant penalty in the space devoted to housing the optical components of the laser system, that is, the output components are all substantially larger than the amplifier cross section. Typically, the cost to manufacture laser-quality optical components increases more rapidly than their cross sectional area, so both space and component costs are rapidly increased by this approach.

In the application of soft x-ray lithography, it is not necessary that all of the x-rays required to expose a mask pattern onto a suitable photoresist be delivered to the photoresist in a single pulse. Nagel, et al., have demonstrated multipulse x-ray lithography exposures using a repetitively pulsed Nd:YAG laser (Applied Optics 23, 1428 (1984)). The laser system used in this work had a pulse repetition rate of 10 Hz, but required 20 minute exposure times into PBS photoresist as a result of the low intensity laser pulses used. Each laser pulse was separated in time by an interval which was long compared to the energy storage time in the amplifier. Thus, that system was not efficient.

In modern optical step-and repeat lithography machines, the time required to deliver ultraviolet light to achieve satisfactory photoresist exposures is typically in the order of a few hundred milliseconds or so. Therefore, an x-ray step-and-repeat lithography machine would be attractive for use in fine line production lithography, so long as the total exposure time is of the order of a few hundred milliseconds or less. Thus, in the operation of the laser system 12, the sequence of laser pulses must be produced by oscillator 172 within a time window of less than a few hundred milliseconds for the purpose of maximum lithographic system efficiency.

Optimization of both x-ray production and laser system efficiency requires consideration of several factors. To insure that a high fraction of the energy obtained from a multistage, pulsed laser amplifier system will be focusable to a high intensity, one or more spatial filters are typically included in the laser system. A spatial filter typically consists of a pair of positive lenses separated by the sum of their individual focal lengths, with a small pinhole located at the common focus. (See, for example, Hunt, et al., Applied Optics 17, 2053 (1978)). In high peak power systems designed for x-ray production, the laser intensity near the common focus will be so high as to cause air breakdown and a consequent loss of transmission through the filter. Thus, spatial filters in this application are typically evacuated. Nevertheless, some portion of the laser energy may strike the sides of the pinhole causing a plasma to form and expand into the pinhole. Such plasma formation may render the pinhole opaque until sufficient time elapses to allow the plasma to dissipate. This dissipation time limits the rate at which successive pulses may be propagated through the laser amplifier chain. If the hot material from the pinhole walls has an average velocity of 50,000 cm/sec (corresponding to approximately 1000 degrees K), then a pinhole of typically 200 microns in diameter would require a minimum of from 200-400 nsec to clear. This sets a lower limit on the interpulse spacing.

This lower limit is consistent with the time required for the x-ray emitting plasma formed at the surface of the laser target to dissipate and thus to permit the unobstructed formation of a new, x-ray emitting plasma by a subsequent laser pulse. The formation of a hot plasma by a focussed laser pulse onto a solid surface is typically accompanied by the production of a small crater in the solid material. Subsequent laser pulses focussed into such a crater show increased x-ray production efficiency as described in U.S. Patent Application Serial No. 669,440, filed November 11, 1984.

In a pulse-pumped, flashlamp driven laser system such as neodymium, the overall optimum conversion of power supply electrical energy into stored laser energy occurs when the flashlamp current pulse has approximately the same duration as the characteristic laser energy storage time of the amplifying medium. This sets an upper limit on the interpulse spacing for best efficiency.

Referring now to Figures 15 and 16A and 16B, as connected as shown in Figure 16, the control system 20 of the subject invention will now be described. The heart of control system 20 is a pair of central processing units (CPU) 308 and 310. CPU 308 may be an HP 300 minicomputer manufactured by Hewlett Packard of Palo Alto California, and generally is used to control the wafer handling system 18. CPU 310 may be an 8088 type microprocessor manufactured by Zendex or equivalent and generally controls the remaining apparatus and timing within the system. CPU 308 is connected to a pair of buses 312 and 314. Bus 312 interconnects CPU 308 with various portions of wafer handling system 18, such as the stepper motors 316, laser interferometer 318, gap adjust mechanisms 320 and stage motion mechanisms 322. Bus 314 connects CPU 308 and CPU 310 so that they may communicate with each other. Further, a printer 324, photo multiplier tube (PMT) 326 and alignment mechanisms 328 are connected to bus 314.

CPU 310 is further connected to a bus 330 to which a plurality of different components receive commands from or provide information to CPU 310. These include slab laser 332, utilities 334, oscillator 336, loader 338, target 340, diagnostics 342, debris control 344, displays 346 and keyboard 348.

Referring now to Figures 16A and 16B, a more detailed diagram of the control system 20 of Figure 15 is shown. It should be noted that Figures 16A and 16B should be placed together in the manner shown in Figure 16. In Figure 16A, the busses 312 and 314 of Figure 15 have been combined into a single bus 314, from which bus 312 exits.

CPU 308 is coupled to bus 314 to provide various signals to both CPU 310 and the various blocks to the left

of bus 314. These blocks include the laser interferometer 318, which provides wafer position and error signal back to bus 314. The alignment circuitry 328 is shown as an X motion alignment system 328A and a Y motion alignment system 328B, each of which receives destination and tolerance signals and provides a current position signal. Finally, the PMT system responds to the set gain and set threshold signals applied thereto from CPU 308 over bus 314.

Bus 312 couples bus 314 to a 32 bit interface circuit 350, which provides timing signals to the gap adjust circuits, shown as tip tilt 320C, cross mask 320A and object positioner 320B. In addition, timing signals are provided to the stepper motors 316, the shutter 322A, and the wafer load 322B, the latter two of which form a part of the stage motion device, shown in Figure 15.

CPU 310 responds to signals from CPU 308, as well as provides signals thereto, over bus 314. In addition, CPU 310 provides a Ready For Shot signal to oscillator 336 and responds to a Shot Complete signal from oscillator 336. Oscillator 336 may be the electronics associated with laser oscillator 172. In addition, CPU 310 provides the Load Mask and Unload Mask signals to Mask Load circuit 338 and responds to the Mask Ready signal from circuit 338. Lastly, CPU 310 responds to the Go To Cassette and Go To Exp Pos signals from Mask Load circuit 338.

CPU 310 provides a System Initialized signal to each of the various circuits 336, 338, 332A, 344, 332B, 342, 334B, 334E, 340A, 340B, 340C, 334A, 334D, 334B and 334C within system 20. Upon the occurrence of the System Initialized signal, each of the circuits is initialized to perform its intended function. The System Initialized signal is provided during the initialization of system 10 described hereafter with respect to Figure 17A and 17B.

Oscillator 336 responds to the Ready For Shot signal from CPU 310 and various status signals, such as the Distilled Water Temperature status signal from DI Water circuit 334A, the Helium status signal from Helium circuit 334D and the Target Status signal from Focus circuit 340B. Assuming all of the status signals are proper, Oscillator circuit 336, in response to the Ready For Shot signal, causes the laser pulse train, previously explained, to be provided and issues the Shot Complete signal to CPU 310. In addition, the Shot Complete signal is provided to the Debris Control circuit 334, the Target Position circuit 340C and the Target Load circuit 340A. In order to control the provision of the laser pulse beams 24 and 24A, Oscillator circuit 336 responds to and provides a plurality of signals within the system. The signals provided by the Oscillator circuit 336 include the Q-Switch On/Off signal, the Interlock Relay signal, the Start signal, the Set Q Switch voltage, the Set PFN voltage, the Simmer Trigger signal, the Fire Q Switch Voltage signal, the Trigger Lamps signal, the Trigger Pockels Cell signal and the Start Amplifier Charge signal. Oscillator 336 responds to the Main Power Interlock signal, Door Interlock Signal, Thermal Interlock signal, the Flow Interlock signal, the Q-Switch Voltage Monitor signal, the Simmer Monitor signal, the Q Switch Monitor 1 and Q-Switch Monitor 2 signals and the PFM Voltage Monitor signal.

Referring now to Figure 16B, the slab amplifier circuit 332A responds to the Glycol and Water Flow Status and Glycol and Water Temperature Status signals, as well as the Vacuum System Status, DI Water Flow Status and DI Water Temperature Status signals and Pockels Cell Status signal from Pockels cell circuit 332B. The slab amp circuit 332A further responds to external signals, including the External Trigger signal and the External Controller Voltage signal. Other information provided the slab amp circuit 332A includes the AT Volt signal, the HV Down Confirmation signal, the Lamp Misfire signal, and the Door Interlock signal. Slab amp 332A provides control signals to turn on the flash lamps of amplifier 188 shown in Figure 11, including the Ramp Up and Ramp Down signals, the Trigger Inhibit signal and the Laser Energy Off signal. In addition, the HV On and HV Off signals are provided from slab amplifier circuit 332A.

Pockels cell circuit 332B responds to the System Initialized signal from CPU 310 and provides the Pockels Cell Status signal to slab amplifier circuit 332A, in response to the Trigger Pockels Cell signal provided thereto from oscillator circuit 336. In addition, Pockels cell circuit 332B receives the Pockels Cell Voltage Down and Pockels Cell OK signals from circuits associated with the Pockels Cells 216 and 252, shown in Figure 11.

The Diagnostic circuit 342 responds to the System Initialized signal, the Laser Output Diode, X-ray Output Diode, Oscillator Output Diode, and Trigger PC signals and provides the Adjust Wave Plate signal.

The Vacuum Control circuit 334E responds to the Systems Initialized signal and the Exposure Tank Pressure, Spatial Filter Pressure, Pump Enclosure Interlock and the Door Interlock signals and provides the Vacuum System Status signal to Slab Amplifier circuit 332A. In addition, Vacuum Control circuit 334E provides the Valve Open/Closed signal and the Pumps On/Off signals.

Target Load circuit 340A responds to the System Initialized signal and the Shot Complete signal from Oscillator 336. In addition, Target Load circuit 340A responds to the Sense Target Presence signal, the Sense Magazine Down Loader signal, the Sense Magazine In Up Position signal and provides the Load New Target signal, Unload Used Target signal, Load Target Magazine signal and Unload Target Magazine signal.

Focus circuit 340B responds to the System Initialized signal from computer 310 and the Target Ready Signal from Target Position Circuit 340C. In addition, Focus circuit 340B responds to the Sense Z Position Target signal and provides the Sense Z Position Of Target signal and the Target Status signal.

Target Position circuit 340C responds to the System Initiate signal and the Shot Complete signal and provides the Increment X Position and Increment Y Position signals to the target mechanisms.

DI Water circuit 334A responds to the System Initialized signal and the Oscillator Temperature Sense Signal, Oscillator Flow Sensor signal, Slab Amplifier Temperature Sensor signal and Slab Amplifier Flow Sensor signal. Distilled water control circuit 334A provides the DI Water Temperature Status signals and DI Water Flow status

signals previously described.

Helium Control circuit 334D responds to the System Initialized signal and the Sense Input Valve and the Sense Helium output pressure signals. Helium control circuit 334D provides the Helium System Status signal to oscillator 336 and the Open/Closed Input Valve signal and the Helium Pumping System On/Off signals to control the helium pressure.

Air Interlock control circuit 334C responds to the System Initialized signal, the Mask Cassette Out signal and the Mask Cassette In signal, the Mask In Place signal and the Outer Door Closed/Open Status signal. Air Interlock control circuit 334C provides the Unload Stepper Output, Load Stepper Output, Unload Stepper Input and Load Stepper Input control signals. In addition, Air Interlock control circuit 334C provides the Closed/Open Interdoor, Closed/Open Outer Door, Pump Out Entry, Inner Door Closed/Open and Pressurized Entry control signals.

Glycol and Water control circuit 334B responds to the Initialize System signal from CPU 310 and the Leak Detect 1, the Leak Detect 2, a pair of Oscillator Flow Sense signals and a pair of Slab Amplifier Flow Sense signals and provides the Glycol and Water Temperature Status and Glycol and Water Flow Status signals to slab amplifier control circuit 332A.

Debris Control circuit 344 responds to the System Initialized signal and the Shot Complete signal as well as the Sense Debris Shield and Pockels Cell Trigger signal to provide an Advanced Shield signal to move the membrane shield 77 over the target to stop the dust particle debris.

Mask Load Control circuit 338B responds to the System Initialized signal and the Unload Mask and Load Mask signals from CPU 310. In addition, Mask Load Control circuit 338B responds to the Cassette Down Place 1 signal and the Sense Mask signal provided thereto from the mask moving mechanisms. Mask Load control circuit 338B provides the Go To Cassette and Go To Exp. Position signals to CPU 310 and additionally provides the Electromagnet On/Off signal to Go To Mask Slot signal, the Give Mask To Chuck signal and the Get Mask From Chuck signal.

As can be appreciated when viewing figures 16A and 16B together, the control of the system is accomplished by computer 310 and the program therein which provides certain signals at certain times to cause certain events to happen. Other things, once initiated, occur automatically in sequence based on each of the various control circuits communicating with one another or with certain transducers throughout system 10.

Examples of the program control caused by CPU 310 on the overall system are shown in Figures 17A, 17B, 18, 19, 20 and 21. Referring now to Figure 17A and 17B, the Initialize Program will be described. This program is executed whenever power is initially applied to the system.

First, according to block 360, a determination is made as to whether all power has been turned on. If the answer is no, then according to block 362, an error message is printed indicating that power is not applied and the program aborts. Assuming that at block 360 power was determined to be on, then according to block 364, the position of the xy stage, which is the chuck 60 of wafer handling system 18, is digitized.

Next, according to block 366, all stepper motors are returned to the home position and the determination is made, as indicated at block 368, whether there are any motor errors. If so, the error message is printed and the program aborts. Assuming no motor errors, then, according to block 372, the laser safety interlocks are digitized and, according to block 374, a determination is made whether the digitized laser interlocks are correct. If not, then according to block 376, the printer prints an error message and recommended operator action. Next, according to block 378, a determination is made whether the operator has commanded abort. If so, then according to block 380, the abort action occurs. If at block 378 the operator had taken the recommended corrective action, a return to block 372 occurs and the laser interlocks are redigitized and, as indicated at block 374, rechecked.

Once the interlocks are determined to be correct at block 374, then according to block 382, distilled water is turned on and a message is printed so indicating to the operator. Next, according to block 384, the distilled water interrupt is enabled and according to block 386 the laser nitrogen is turned on and the message is printed to notify the operator of such action. Next, according to block 388, the laser nitrogen interrupt is enabled.

Next, according to block 390, the glycol cooling is turned on and a message is sent so indicating to the operator. Then, according to block 392, the glycol interrupt is enabled and according to block 394, all shutters are closed. Thereafter, as indicated at block 396, a determination is made whether all shutters have been closed. If not, according to block 398, an error message is printed and an abort occurs. Assuming the shutters were determined to be closed at block 396, then, as indicated at block 400, the laser oscillator is turned on at one-half power and according to block 402 a message so indicating is sent to the operator. Next, according to block 404, the slab amplifier is turned on at one-half power, and according to block 406, a message so indicating is sent to the operator.

Next, according to block 408, the frog arm is exercised. The term "frog arm" is the name given to the material handling system 14 robot 28 and arm 30, shown in Figure 1A. As previously mentioned, the arm 30 of robot 28 moves the masks, target and wafers within system 10. Next, according to block 410, a determination is made whether there are any frog arm errors, and, if so, the error message is printed and an abort occurs.

Assuming that the frog arm is properly operating, as determined at block 410, then according to block 414, the two SMIF port elevators are raised. The SMIF port is the port which container 34 shown in Figure 1 is inserted and includes an elevator therein for moving the items present in the port to a position to be loaded

onto the frog arm. Continuing at block 416 in Figure 17B, next, a determination is made whether the SMIF elevators are in the up position. If not, according to block 418, an error message is printed and according to block 420, the operator is prompted to continue or to abort. If at block 422 it is determined that the operator determined to abort, then block 424 indicates the abort. If at block 422 it were determined that the operator desired to continue, then according to block 426 the status of each of the SMIF ports is stored and then a continuation at block 428 occurs. At block 428 the target magazine status is checked and next at block 430 a determination is made whether targets are present. If it is found at block 430 that no targets were present, then according to block 432 the operator is prompted to load targets into one SMIF port. Next, at block 434, a determination is made whether the targets are ready for loading. If not, a return to the beginning of block 434 occurs until such time as it is determined that targets are ready for loading. Once targets are ready for loading, then according to block 436, the frog arm loads the targets from the SMIF port to the storage tray and a return to block 430 occurs. At this point it is determined that the targets are present.

Continuing with block 438, the mask magazine status is checked and, at block 430, a determination is made whether masks are present. If no masks are present, then according to block 442, the operator is prompted to load the masks in the SMIF port. In addition, the message will inform the operator how many masks are to be loaded and, then at block 444, a determination is made whether the masks are ready for loading into the system. Until such time as they are, the procedure remains at block 444. Once the masks are ready for loading into the system, then according to block 446, the frog arm is instructed to get the top most mask from the SMIF port. Next, according to block 448, the mask ID is read from the tray and, according to block 450, the frog arm stores the mask in the storage tray and records the position with respect to the ID read. Next, according to block 452, a determination is made whether the last mask has been stored. If not, a return to block 446 occurs and blocks 446, 448, 450 and 452 are repeated until the last mask has been stored in the storage tray and its position recorded in connection with the mask ID number. Once the last mask has been stored, then a return to block 440 occurs.

Once it is determined at block 440 that the masks are present, then, according to block 452, the operator is sent a message that the system has been initialized and according to block 456 the main menu is displayed. The initialization program then continues at point A as the main operating program, which is shown in Figure 18.

Referring now to Figure 18, the main system operating flow diagram will be described. This diagram is used in conjunction with the displayed main menu and has been labeled as program A for convenience herein. Generally, program A, or the system operating program, is continually repeated until the operator makes a selection from the main menu, in which case a branch to one of the other programs B through L occurs. When that selected program has been executed, a return to program A occurs and the program waits for the next operator command.

First, according to block 458, the user interface is initiated and according to block 460 the screens are cleared. Then, according to block 462, the user menu is displayed. Next, according to block 464, a determination is made whether a function request has been entered pursuant to the user menu. If not, all of the error conditions are checked, according to block 466, and if an error has been reported, as determined at block 468, the error condition is printed and an abort occurs. If no error had been reported at the determination made at block 468, a return to block 464 occurs and a wait for a function request or an error report occurs.

Once a function request has been found at block 464 a continuation with blocks 472-492 (even numbers only) occurs. Each of the blocks 472-492 (even numbers only) represents each of the various functions which can be requested. Whenever one of the functions has been determined to be found at one of blocks 472-492 (even numbers only), then a branch to a respective program B through L occurs.

The following functions correspond to the following programs which can be selected according to blocks 472-492 (even numbers only):

Block No.	Function	Program	
472	Load Machine Data	B	
474	Load Target	C	5
476	Load Mask Into Machine	D	
478	Load Mask	E	
480	Process Wafer	F	10
482	Print Data	G	
484	Change Data	H	
486	Read Status	I	15
488	Change Status	J	
490	Diagnostics	K	
492	Exit Menu	L	20

Examples of programs B, C and D, representing respectively, the Load Machine Data, Load Target and Load Masks Into Machine programs, are hereafter given in Figures 19, 20 and 21. Others of the programs can be developed, along the lines shown in Figures 19, 20 and 21 and the accompanying descriptions thereto, for the programs E-L. 25

Referring now to Figure 19 the Load Machine Data program B is shown. First, according to block 494, the machine data is loaded from the file on the disk associated with computer 310. Next, according to block 496, the machine variables are updated based on information determined during the error and status checks. 30 Lastly, according to block 498, the current machine operating variables are displayed and printed for the operator's benefit. Then a return to program A shown in Figure 18 occurs.

Referring now to Figure 20, program C, relating to the loading of the targets is shown. First, according to block 500, a determination is made whether target storage space exists. If not, the message "Target Storage Full" is displayed and a return to the main program A occurs. 35

Assuming at block 500 that target storage space was determined to exist, then, next, according to block 504, a determination is made whether there are targets in the front SMIF port. If not, a determination is made at block 506 whether there are targets in the side SMIF port. If both determinations at blocks 504 and 506 were no, then, according to block 508, the operator is prompted to load targets into one SMIF port and, according to block 510, a determination is made if the targets are ready. If not, a continuation with block 510 results until such time as it is determined that the ready condition exists. At that point, a clear signal is issued and a return to block 504 occurs. If at block 506, it were determined that the targets were in the side SMIF port, then according to block 512 the side SMIF port is defined as the input port. If at block 504, it were determined that the targets were in the front SMIF port, then according to block 514, the front SMIF port is defined as the input port. 40

In either case, a continuation at block 516 occurs and the frog arm is commanded to move in the Z, or vertical, direction to the SMIF plate height. Next, at block 518, the frog arm is commanded to rotate to the designated input port defined at block 512 or 514. Then, at block 520, the frog arm is extended to reach the SMIF plate at the designated input port and, at block 522, the frog arm lowers the elevator. Next, at block 524, the frog arm is retracted and, at block 526, a determination is made whether the elevator is down. If not, an error message is printed, as indicated at block 528, and abort occurs, as indicated at block 530. Assuming the determination was made at block 526 that the elevator was down, then according to block 532, the top most target is located. Next, according to block 534, the z distance required for the frog to move to service this target is calculated and at block 536, the frog arm is moved to that calculated height, minus a small clearance. Next, according to block 538, the frog arm is extended to the target tray and at block 540, the frog arm is moved up by the clearance amount. 45

Next, according to block 542, the vacuum is turned on for the frog arm hold down, so that it can take the target and, at block 544, the frog arm is retracted to the center. Then, at block 546, the frog arm is rotated to the storage area and, at block 548, the frog arm is extended to the storage tray. Then, at block 550, the vacuum chuck is turned off so that the target can be stored and, at block 552, the frog arm is lowered to clear the target and, at block 554, the frog arm is retracted back to the center to be out of the way. 50

Next, at block 556, a determination is made whether there are any more targets. If not, a message is displayed that the target load is complete and a return to the main program A occurs. If at block 556 it were determined that there were more targets to be loaded, then, at block 560, a determination is made whether there is target space available. If not, then according to block 562, the message "Target Storage Full" is 55

displayed and a return to the main program A occurs. If, at block 560, it were determined that there was additional storage space, then, at block 564, the frog arm is rotated back to the input port and a return to block 536 occurs and the same process beginning with block 536 is repeated until such time as a return to the main program, after either block 558 or block 562, results.

5 Referring now to Figure 21, program D, relating to loading masks into the machine, is shown. Program D is identical to program C, with the exception that the operations occur with respect to masks instead of targets and with the further exception of the addition of blocks 566, 568, 570 and 572 between blocks 544 and 546. Block 566 indicates that the frog arm, which was retracted to the center at block 544, is rotated to the bar code reader and, then, according to block 568, the frog arm is extended to the bar code reader. Then, at block 570, the mask ID is read by the bar code reader and, at block 572, the ID is stored with respect to the storage position. Then, the program as previously described continues at block 546, where the frog arm is rotated to the storage area and the mask is stored.

As will be appreciated from the above description, according to one aspect of the present invention there is provided an X-ray lithography system including target means and resist covered wafer means; an evacuated chamber having a window sealed in the side wall thereof, and means for generating and focusing a laser beam through said window towards a focal point characterized by said chamber further having a first opening at one end thereof and a second opening at the other end thereof; means for holding and moving said target means so that a target surface of said target means moves coincident with said focal point, said means for holding and moving said target means further forming a vacuum seal around said first opening while holding and moving said target means; means for holding and moving said resist covered wafer means and for forming a vacuum seal around said second opening while holding and moving said wafer means; and control means for controlling the generation of said laser beam, the evacuation of said chamber and the movement of said target holding and moving means and said wafer holding and moving means.

The said means for holding and moving said wafer means may include air bearing and vacuum sealing means.

The said means for holding and moving said target means may also include air bearing and vacuum sealing means.

The said first opening may be encompassed by a first flat surface; said means for holding and moving said target means including a second flat surface, at least a portion of which is aligned with said first flat surface; one of said first or second flat surfaces including a flow path therethrough attached to pressure providing means for maintaining a separation between said first and second flat surfaces.

One of said first or second flat surfaces may include a second flow path therethrough attached to evacuation means, said second flow path being positioned from said maintained separation at a location between said first flow path and said first opening.

35 The second flow path may include a ring recessed into said one surface.

The said recessed ring may surround said first opening.

The said recessed ring may surround said first opening during the movement of said target mean.

The said second opening may be encompassed by a first flat surface; said means holding and moving said wafer means including a second flat surface, at least a portion of which is aligned with said first flat surface; and one of said first or second flat surfaces including a flow path therethrough attached to pressure providing means for maintaining a separation between said first and second flat surfaces.

One of said first or second flat surfaces may include a second flow path therethrough attached to evacuation means, said second flow path being positioned from said maintained separation at a location between said first flow path and said second opening.

45 The said recessed ring may surround said second opening. Thus, the said recessed ring may surround said second opening during the movement of said wafer means.

It will also be appreciated that, according to another aspect of the present invention, there is provided a vacuum seal and air bearing for use in an X-ray lithography machine in which X-rays are generated in an evacuated chamber by focusing a laser beam at a target with sufficient power to create an X-ray emitting plasma, said machine further including an X-ray mask and a resist covered substrate to which X-rays, patterned by said mask, are to be provided, said evacuated chamber having at least one opening therein through which at least one of said target, mask and substrate are positioned, said seal and air bearing including means for holding one of said target, mask or substrate characterized by a flat surface extending from said evacuated chamber opening; pressure providing means for maintaining one of said means for holding said target, said mask or said substrate spaced from said flat surface by providing gas into a first flow path between said flat surface and said one of said means for holding said target, said mask or said substrate; and evacuation means for removing gas provided by said pressure providing means and gas from within said evacuated chamber through a second flow path positioned between said opening and said pressure providing means path.

60 The said pressure providing means may include a pair of flow paths adjacent to one another each for having gas, under pressure greater than atmospheric pressure, applied therethrough.

The first flow path or the said pair of flow paths may extend from pump means to the space created by said pressure providing means.

65 The said means for holding may include a flat surface and said pair of flow paths may extend from between said flat surface of said means for holding and said flat surface extending from said evacuated chamber.

The said flat surface of said means for holding may extend over an area encompassing said opening.

The said means for holding may hold one of said target or said substrate and further moves said held one of said target or substrate relative to said plasma position.

The said flat surface of said means for holding may extend over an area sufficiently large to encompass said opening during movement of said means for holding.

The said pair of flow paths may each include an encompassing opening in said flat surface to which they extend of sufficient size to encompass said opening.

The said encompassing openings in said pair of flat flow paths may be sufficiently large to encompass said opening during movement of said means for holding.

It will further be appreciated that, according to a further aspect of the present invention, there is provided a method of fabricating semiconductor devices using X-rays generated in the interior of an evacuated chamber by focusing a laser beam pulse on a held target with sufficient power to form an X-ray emitting plasma, said emitted X-rays exposing a pattern on a held resist covered semiconductor substrate, said method being characterized by the steps of moving, while forming a vacuum seal around a first opening in said chamber, said target means so that a target surface of said target means moves in said chamber interior coincident with the focal point of said focused laser beam; and moving, while forming a vacuum seal around a second opening in said chamber, said substrate from one exposure position to the next adjacent exposure position.

The said step of moving said target may be characterized by the steps of generating a high pressure zone between said chamber and the means for holding said target; and evacuating a region between said zone and said evacuated chamber interior.

The said step of moving said target may also be characterized by the step of forming an air bearing and seal between said chamber and the means for holding said target.

The said step of moving said substrate may be characterized by the steps of generating a high pressure zone between said chamber and means for holding said substrate; and evacuating a region between said zone and said evacuated chamber interior.

The said step of moving said substrate may be further characterized by the step of forming an air bearing and seal between said chamber and the means for holding said substrate.

It will be additionally appreciated that, according to yet a further aspect of the present invention there is provided an X-ray lithography system including a resist covered substrate; a mask having a pattern thereon; a target aligned with said mask and substrate; and laser beam pulse producing means, including oscillator means and amplifier means, for providing a plurality of amplified laser beam pulses to said target with sufficient power to cause an X-ray emitting plasma to be created, said X-rays being provided through said mask to cause a pattern of X-rays to expose said resist covered substrate, said amplifier means including a glass slab and a flashlamp for providing optical energy to said slab for storage by said slab for a given time period, characterized by said oscillator means generating a plurality of unamplified laser beam pulses within said given time period.

The said laser beam producing means may further include spatial filters through which each laser beam pulse travels and causes a plasma to be created therein, which plasma lasts for a certain time period, less than said given time period, each of said plurality of unamplified laser pulses being separated by at least said certain time period.

The said laser beam producing means may include laser beam pulse directing means for directing each of said unamplified laser beam pulses through said amplifier a plurality of times during said given time period to obtain said amplified laser beam pulse.

Each of said laser beam pulses may be directed to the same point on said target.

The said laser oscillator may be a Q switched laser oscillator.

The said glass slab may have two parallel faces into which said optical energy from said flashlamps is directed and two laser path faces positioned at an angle to said parallel faces, said unamplified laser beam pulses being directed into one of said laser path faces and said amplified laser beam pulses being provided from the other one of said laser path faces. Each of said plurality of laser beam pulses may be separated from the next occurring one of said laser beam pulses by at least 100 nanoseconds.

It will be appreciated that, according to yet another aspect of the present invention, there is provided a method of providing amplified laser energy to an object to be irradiated, said laser energy being amplified by a laser amplifier of a type which receives optical energy and stores said received optical energy for a given time interval, said method including the steps of directing optical energy towards said amplifier to energize said amplifier; generating a first laser beam pulse; providing said first laser beam pulse through said amplifier; characterized by generating a second laser beam pulse, within said given time interval after the end of said step of directing; providing said laser beam pulse through said amplifier; and directing said first and second laser pulses from said amplifier to said object.

The said object may be a target of a type from which X-ray emitting plasma may be created, said method further being characterized by the step of directing sufficient optical energy to said amplifier so that each of said first and second laser beam pulses have sufficient power to create an X-ray emitting plasma upon being directed to said target.

The said step of providing said first laser beam may include providing said first laser beam through a spatial filter, thereby creating a plasma in said first spatial filter during a certain time interval, said certain time interval being less than said given time interval, said method being further characterized in that said step of generating

said second laser beam occurs after said certain time interval.

Where the said object is a target, the said step of directing may include directing said laser beam pulses towards said target, creating an X-ray emitting plasma at the point said laser beams intersect said target, placing a patterned X-ray mask in the path of said X-rays, and exposing a resist covered substrate with a pattern of X-ray defined by said mask.

According to yet a further aspect of the present invention, there is provided an X-ray lithography machine for use in the production fabrication of semiconductor devices, said machine operating upon positioned replaceable items, including wafers, masks and targets, in fabricating said devices, said machine including therein an operation chamber in which selected unpositioned ones of said replaceable items are stored in different locations of at least one stack for subsequent positioning on said machine, characterized by common transport means, upon operator command, for removing a selected one of the items from a selected stack location and for transporting and positioning said removed item on said machine, and, upon subsequent operator's command, for removing said selected item from position on said machine back to a selected stack location.

The said common transport means may include a platform and an arm.

The said replaceable items may be stored in a plurality of stacks, each having a plurality of stack locations.

The said common transport means may further include processor means for controlling the movement of said transport means in response to said operator commands.

The said target may be positioned in an evacuated chamber and said common transport means includes means for controlling the evacuation and vacuum release within said chamber.

According to yet another aspect of the present invention, there is provided a method of preparing for operation an X-ray lithography machine in which replaceable items, including targets, masks and wafers, are positioned during operation of said machine, said items being stored in at least one stack of said items when not positioned for operation of said machine, said method being characterized by the steps of removing, upon operator command, a selected one of the items from a selected stack location; positioning said removed item on said machine; and upon subsequent operator's command, moving said selected item from position on said machine back to a selected stack location.

The step of transporting said removed item may be prior to positioning said removed item.

The said target may be positioned within an evacuated chamber, said method further being characterized by the steps of: releasing the vacuum from said chamber prior to said step of positioning; and evacuating said chamber after said step of positioning.

The said items may be stored in a plurality of stacks and said method may be further characterized by selecting the proper stack from which said selected item is to be removed in response to said operator commands. There may also be the step of selecting the proper stack to which said selected item is to be moved from position on said machine in response to said operator commands.

The said step of moving may include the steps of removing said selected item from position on said machine and moving said selected item to said selected stack location.

Claims

1. A high energy laser beam generator (12) including a laser beam oscillator (172) for providing a narrow and low energy laser beam (24) relative to the desired output beam; a face pumped laser amplifier (188) having a path (190) for laser beam energy amplification of a first distance in one direction and a second distance in a perpendicular direction, said second distance being substantially greater than said first distance; first laser beam direction means (174 to 186, 196 to 230) for directing said laser beam generated by said oscillator (172) through said amplifier (188) along one part (left part of Fig. 12) of said path (190) characterized by second laser beam direction means (232 to 306), including beam expander means (232 and 262), for expanding the size of the beam (24) to not greater than said first distance along one axis of said beam (24) and to between said first and second distances along another axis, said second direction means (232 to 306) further including means (240, 244, 246, 256, 258, 260, 270 and 272) for redirecting said expanded laser beam (24) through said amplifier (188) along a second part (right part of Fig. 12) of said path (190), not intersecting said first part (left part of Fig. 12) of said path (190).

2. A generator according to claim 1 further characterized by said beam expander means (232 and 262) including an anamorphic beam expander (234, 236 and 238 and 264, 266 and 268).

3. A generator according to claim 1 or 2 further characterized by said second direction means (232 to 306) further including second beam expander means (280) to expand said beam (24) exiting said amplifier (188) path (190) along said first axis to the same size as expanded along said other axis.

4. A generator according to claim 2 further characterized by said first beam expander means (232 and 262) and said second beam expander means (280) each including an anamorphic beam expander (234, 236 and 238; 264, 266 and 268 and 282, 284 and 286).

5. A generator according to claim 1 or 3 further characterized by said first beam expander means (232 and 262) and said second beam expander means (280) each including a plurality of triangular shaped prisms (234, 236 and 238; 264, 266 and 268 and 282, 284 and 286).

6. A laser beam generator (12) for generating a high power laser beam (24) comprising a laser oscillator (172) for providing an initial laser beam (24); a face pumped laser beam amplifier (188), including a glass slab (190) having two main faces into which optical energy is pumped and a cross sectional area between said two main faces of a certain height separating said two main faces and a certain width perpendicular to and greater than said certain height; first directing means (174 to 186, 196 to 230) for directing said laser beam (24) provided from said oscillator (172) through a first path (left portion of Fig. 12) between the main faces of said slab (190) to obtain a first amplified laser beam (A and B) characterized by means (232 and 262) for expanding said first amplified laser beam (A and B) in a direction oriented with said height to a dimension less than said height and in a direction oriented with said width to a dimension greater than said height and less than said width to obtain an expanded laser beam (C); and second directing means (270 to 276) for directing said expanded laser beam through a second path (right portion of Fig. 12), remote from said first path (left portion of Fig. 12), between the main faces of said slab (190) to obtain said high power laser beam (24, 24A). 5
7. A generator according to claim 6 wherein said first and/or said second directing means (174 to 186, 196 to 230, 270 to 276) includes shutter means (212, 252). 10
8. A generator according to claim 6, or 7 further characterized by said generator (12) further including second means (280) for expanding said expanded laser beam (C) in said direction oriented with said height to a dimension greater than said height to obtain said high power laser beam (24, 24A). 15
9. A generator according to claim 6, 7 or 8 characterized in that said means (232 and 262) for expanding includes at least one anamorphic beam expander. 20
10. A generator according to any of claims 6 to 9 characterized by said first directing means (174 to 186, 196 to 230) including first and second beam expanding means (180 and 206) for expanding a laser beam applied thereto in a substantially symmetrical manner; means (174, 176, 178) for providing said oscillator (172) provided laser beam (24) to said first expanding means (180) to obtain a first expanded laser beam of a dimension less than said height; means (182, 184, 186, 196, 198) for directing said first expanded laser beam (A) through said slab (190) along a first part of said first path (left side of Fig. 12) to obtain an initial amplified laser beam (A); means (200 to 204) for providing said initial amplified laser beam (A) through said second beam expanding means (206) to obtain a second expanded laser of a dimension substantially the same as said height; and means (208, 210, 222 to 228) for directing said second expanded laser beam through said slab (190) along a second part, different from said first part, of said first path (left side of Fig. 12) to obtain said first amplified laser beam (B). 25
11. A generator according to claim 10 wherein said first and second beam expanding means (180 and 206) include spatial filters. 30
12. A generator according claims 10 or 11 characterized in that said first and second parts of said first path (left side of Fig. 12) are adjacent to one another and coextensive with the length of said slab (190). 35
13. A method for generating a high power laser beam (24, 24A) using a face pumped laser beam amplifier (188), including a glass slab (190) having two main faces into which optical energy is pumped and a cross sectional area between said two main faces of a certain height separating said two main faces and a certain width perpendicular to and greater than said certain height, said method including the steps of generating an initial laser beam; directing said generated initial laser beam through a first path (left side of Fig. 12) between the main faces of said slab (190) to obtain an amplified laser beam (B); said method being characterized by the steps of expanding said amplified laser beam (B) in a direction oriented with said height to a dimension less than said height and in a direction oriented with said width to a dimension greater than said height and less than said width to obtain an expanded laser beam (C); and directing said expanded laser beam (C) through a second path (right side of Fig. 12), remote from said first path (left side of Fig. 12), between the main faces of said slab (190) to obtain said high power laser beam (24, 24A). 40
14. The method according to claim 13 further characterized in that said step of directing said generated initial laser beam includes the step of symmetrically expanding said initial laser beam. 45
15. The method according to claim 14 further characterized in that said step of symmetrically expanding said initial laser beam further includes the step of directing said symmetrically expanded laser beam through a third path (path of beam A in Fig. 12), different from said first and second paths (paths of beams B and C in Fig. 12), between the main faces of said slab (190). 50
16. The method according to claim 15 further characterized in that said step of directing said laser beam through said third path includes directing said laser beam through a spatial filter (180 and 206) for symmetrically expanding said beam to a dimension substantially equal to said height. 55
17. The method according to any of claims 13 to 16 further characterized in that said step of directing said expanded laser beam (C) further includes the step of expanding said laser beam obtained from said slab (190) in a direction oriented with said height to be substantially the same as the dimension oriented in the direction associated with said width. 60
18. An X-ray lithography system (10) including target means (26) and resist covered wafer means (58); an evacuated chamber (22) having a window (70, 72) sealed in the side wall thereof, and means (12, 52, 54) for generating and focusing a laser beam (24, 24A) through said window (70, 72) towards a focal point (74) characterized by said chamber (22) further having a first opening (74) at one end thereof and a second opening (92) at the other end thereof; means (78, 82-90) for holding and moving said target means (26) so that a target surface of said target means (26) moves coincident with said focal point (74), 65

said means (78, 82-90) for holding and moving said target means (26) further forming a vacuum seal around said first opening (74) while holding and moving said target means (26); means (18) for holding and moving said resist covered wafer means (58) and for forming a vacuum seal around said second opening (92) while holding and moving said wafer means (58); and control means (20) for controlling the generation of said laser beam (24, 24A), the evacuation of said chamber (22) and the movement of said target holding and moving means (78, 82-90) and said wafer holding and moving means (18).

19. A vacuum seal and air bearing for use in an X-ray lithography machine (10) in which X-rays (56) are generated in an evacuated chamber (22) by focusing a laser beam (24, 24A) at a target (26) with sufficient power to create an X-ray emitting plasma, said machine (10) further including an X-ray mask (94) and a resist covered substrate (58) to which X-rays (56), patterned by said mask (94), are to be provided, said evacuated chamber (22) having at least one opening (74, 92) therein through which at least one of said target (26), mask (94) and substrate (58) are positioned, said seal and air bearing including means (78, 147 or 18) for holding one of said target, mask or substrate characterized by a flat surface (80, bottom of 22 or 122) extending from said evacuated chamber (22) opening (74, 92); pressure providing means (132, 134, 166 334C, 334D) for maintaining one of said means (78, 147 or 18) for holding said target (26), said mask (94) or said substrate (58) spaced from said flat surface (80, bottom of 22 or 122) by providing gas (He, Air) into a first flow path (132, 134, 166) between said flat surface (80, bottom of 22 or 122) and said one of said means (78, 147 or 18) for holding said target (26), said mask (94) or said substrate (58); and evacuation means (128, 130, 164) for removing gas provided by said pressure providing means (132, 134, 166 334C, 334D) and gas from within said evacuated chamber (22) through a second flow path (128, 130, 164) positioned between said opening (74, 92) and said pressure providing means path (132, 134, 166).

20. A method of fabricating semiconductor devices using X-rays (56) generated in the interior of an evacuated chamber (22) by focusing a laser beam pulse (24, 24A) on a held target (26) with sufficient power to form an X-ray emitting plasma, said emitted X-rays (56) exposing a pattern on a held resist covered semiconductor substrate (58), said method being characterized by the steps of moving, while forming a vacuum seal around a first opening (74) in said chamber (22), said target means (26) so that a target surface (bottom of 26) of said target means (26) moves in said chamber (22) interior coincident with the focal point (74) of said focused laser beam (24, 24A); and moving, while forming a vacuum seal around a second opening (92) in said chamber (22), said substrate (58) from one exposure position to the next adjacent exposure position.

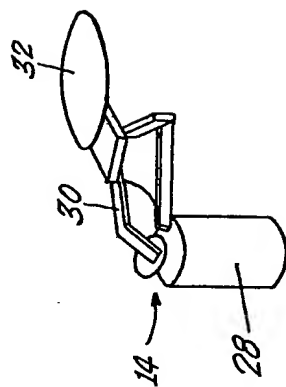
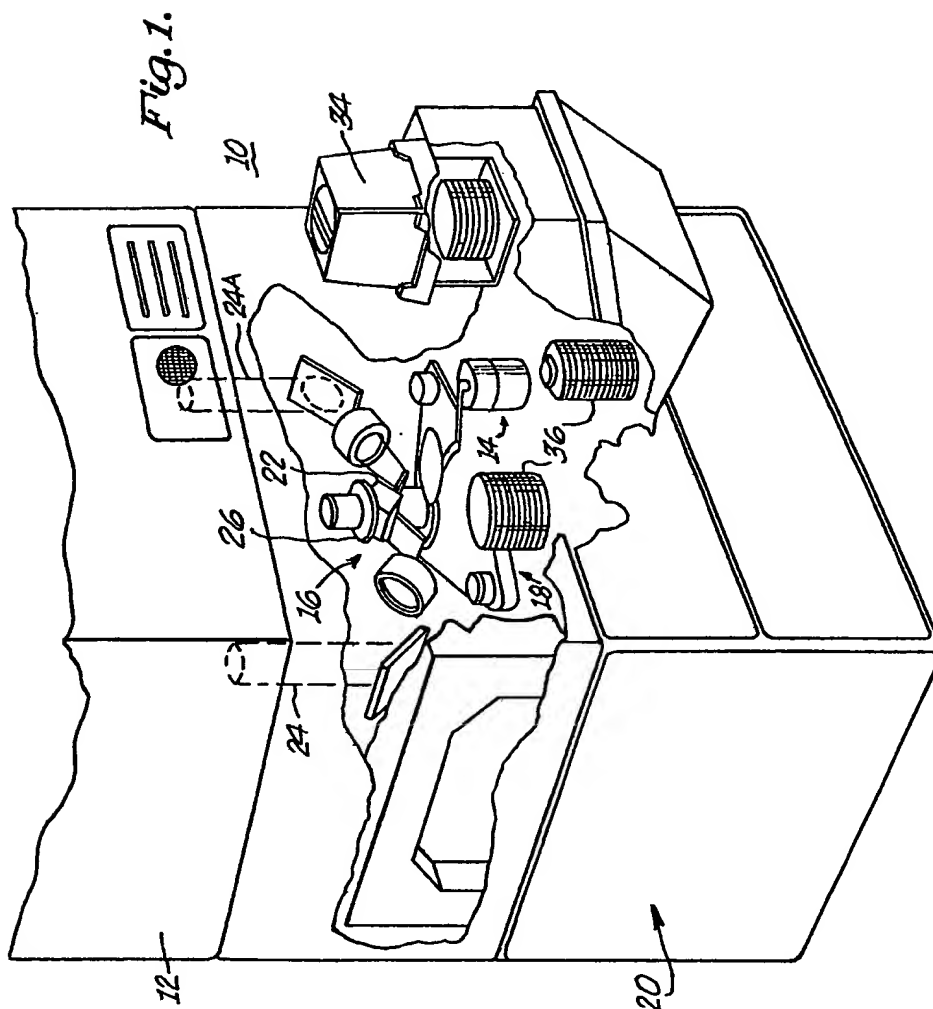
21. An X-ray lithography system (10) including a resist covered substrate (58); a mask (94) having a pattern thereon; a target (26) aligned with said mask (94) and substrate (58); and laser beam pulse producing means (12), including oscillator means (172) and amplifier means (188), for providing a plurality of amplified laser beam pulses to said target (26) with sufficient power to cause an X-ray (56) emitting plasma to be created, said X-rays (56) being provided through said mask (94) to cause a pattern of X-rays (56) to expose said resist covered substrate (58), said amplifier means (188) including a glass slab (190) and a flashlamp (192, 194) for providing optical energy to said slab (190) for storage by said slab (190) for a given time period, characterized by said oscillator means (172) generating a plurality of unamplified laser beam pulses within said given time period.

22. A method of providing amplified laser energy to an object (26) to be irradiated, said laser energy being amplified by a laser amplifier (188) of a type which receives optical energy and stores said received optical energy for a given time interval, said method including the steps of directing optical energy towards said amplifier (188) to energize said amplifier; generating a first laser beam pulse; providing said first laser beam pulse through said amplifier (188); characterized by generating a second laser beam pulse, within said given time interval after the end of said step of directing; providing said second laser beam pulse through said amplifier (188); and directing said first and second laser pulses from said amplifier (188) to said object (26).

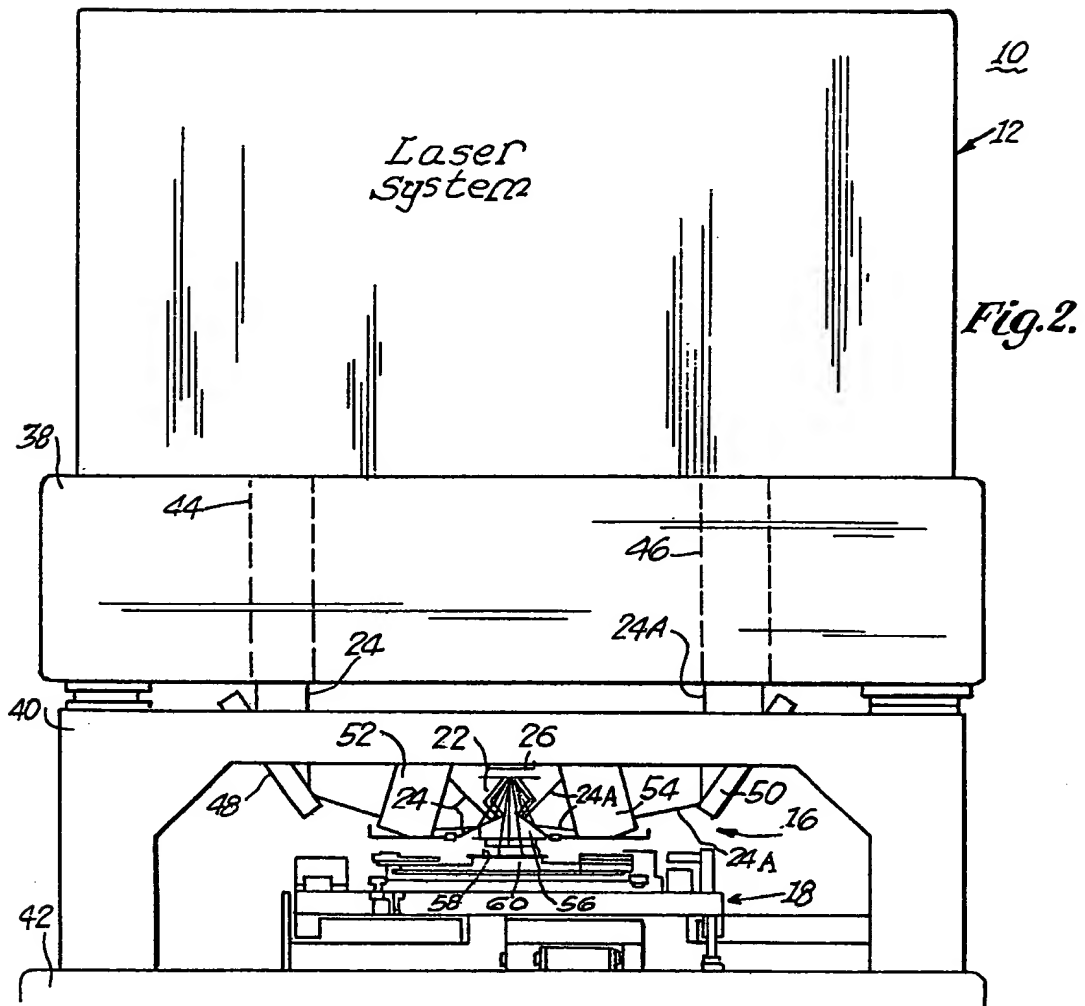
23. An X-ray lithography machine (10) for use in the production fabrication of semiconductor devices, said machine operating upon positioned replaceable items (26, 58, 94), including wafers (58), masks (94) and targets (26), in fabricating said devices, said machine (10) including therein an operation chamber in which selected unpositioned ones of said replaceable items (26, 58, 94) are stored in different locations of at least one stack (36) for subsequent positioning on said machine (10), characterized by common transport means (14), upon operator command, for removing a selected one of the items (26, 58, 94) from a selected stack (36) location and for transporting and positioning said removed item (26, 58, 94) on said machine (10), and, upon subsequent operator's command, for removing said selected item (26, 58, 94) from position on said machine (10) back to a selected stack (36) location.

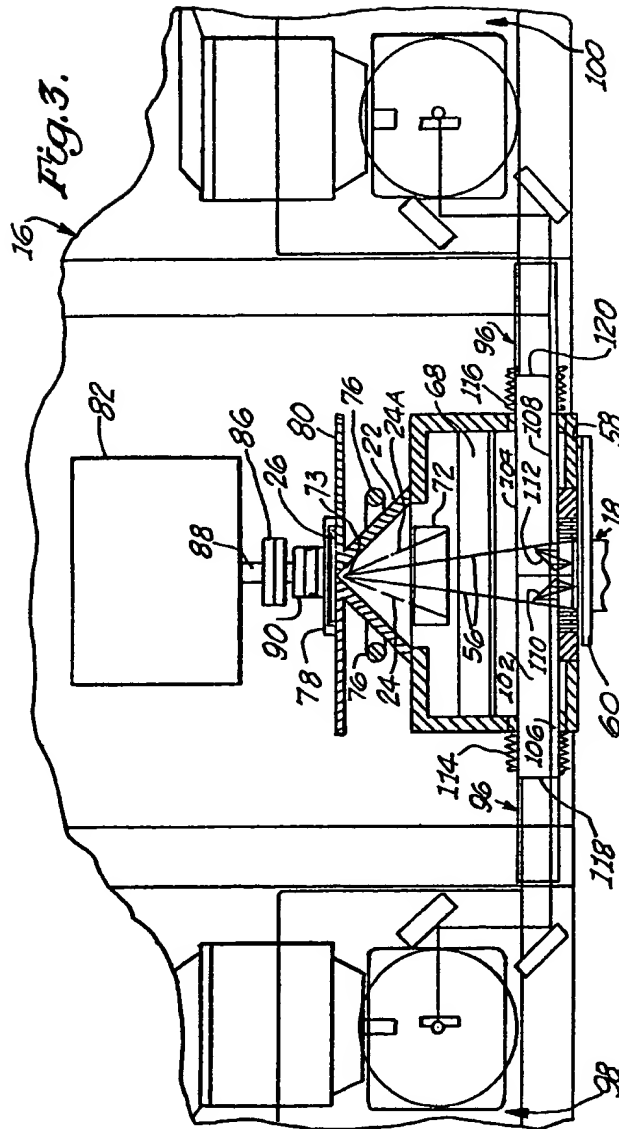
24. A method of preparing for operation an X-ray lithography machine (10) in which replaceable items (26, 58, 94), including targets (26), masks (94) and wafers (58), are positioned during operation of said machine (10), said items being stored in at least one stack (36) of said items (26, 58, 94) when not positioned for operation of said machine (10), said method being characterized by the steps of removing, upon operator command, a selected one of the items (26, 58, 94) from a selected stack (36) location; positioning said removed item (one of 26, 58, 94) on said machine (10); and upon subsequent operator's command, moving said selected item (one of 26, 58, 94) from position on said machine (10) back to a selected stack (36) location.

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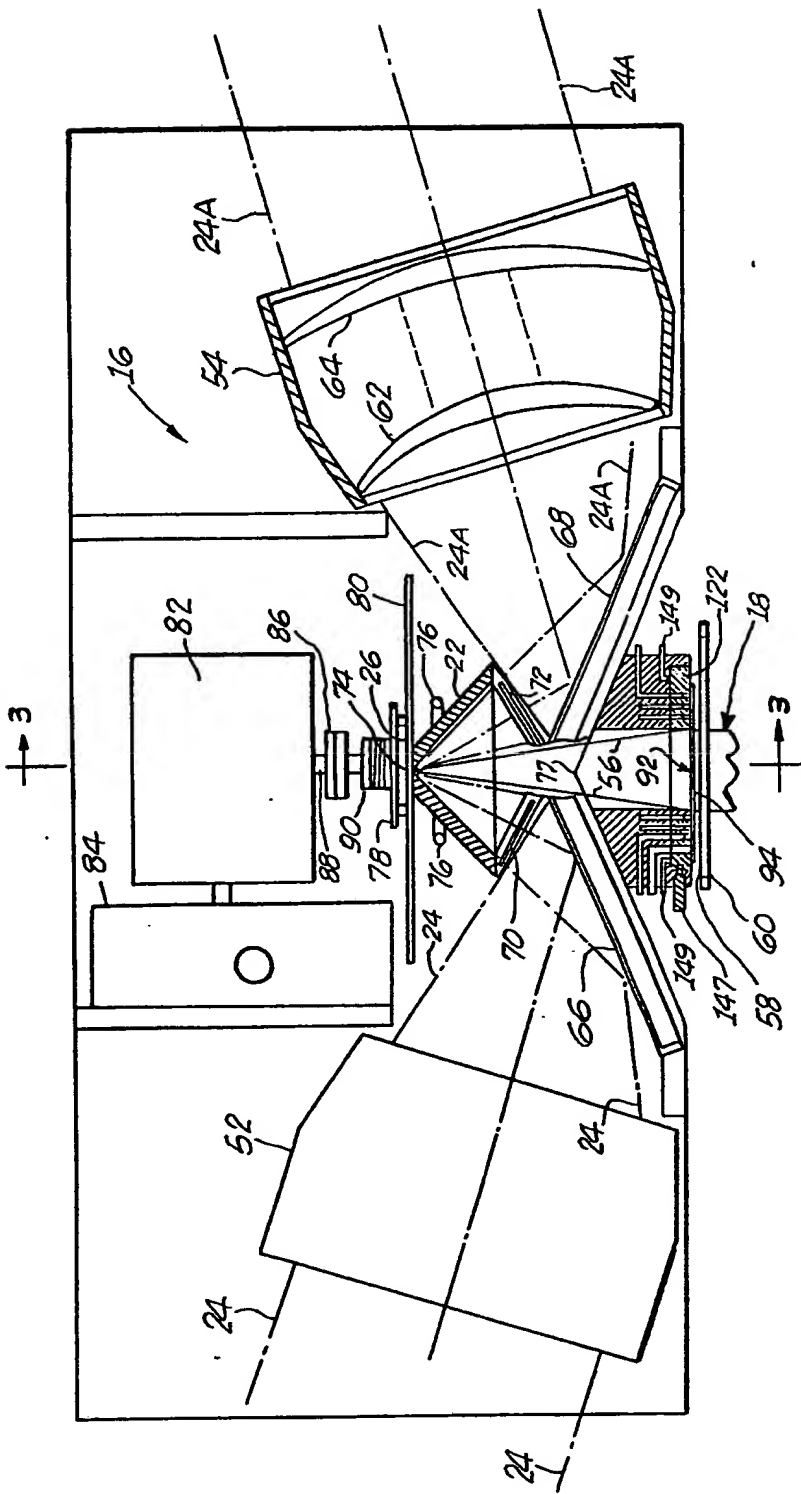


Fig. 4.

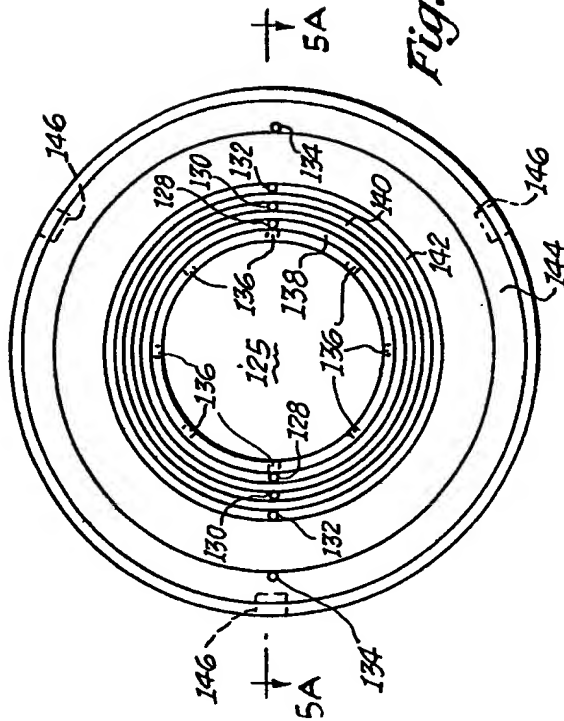


Fig. 5.

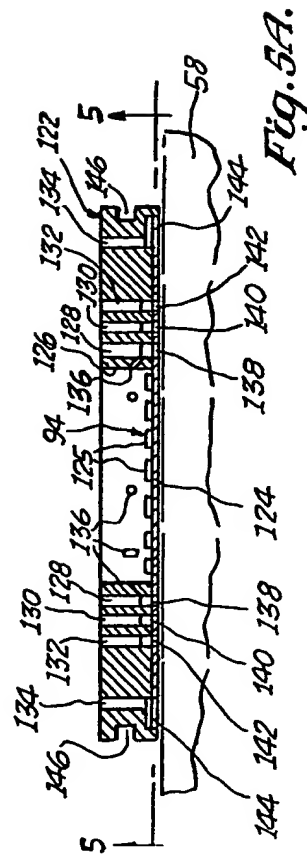


Fig. 5A.

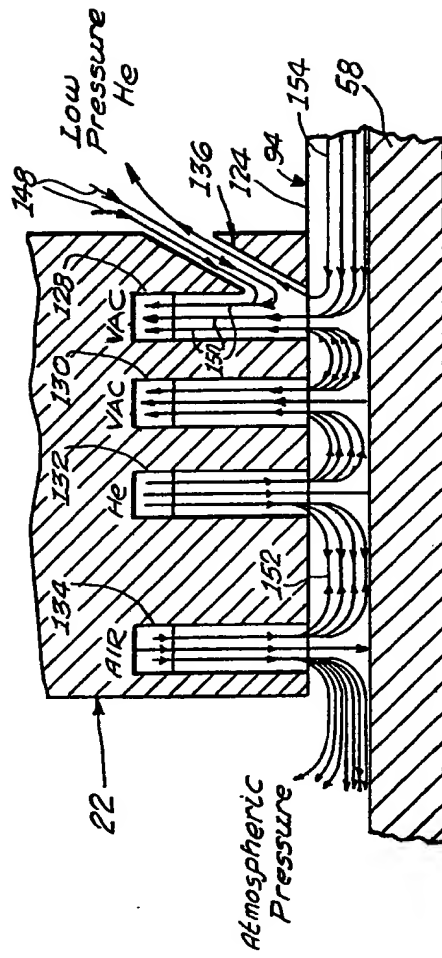
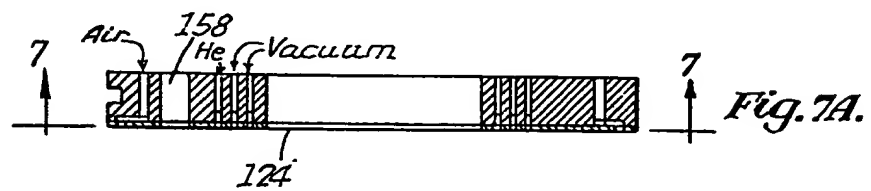
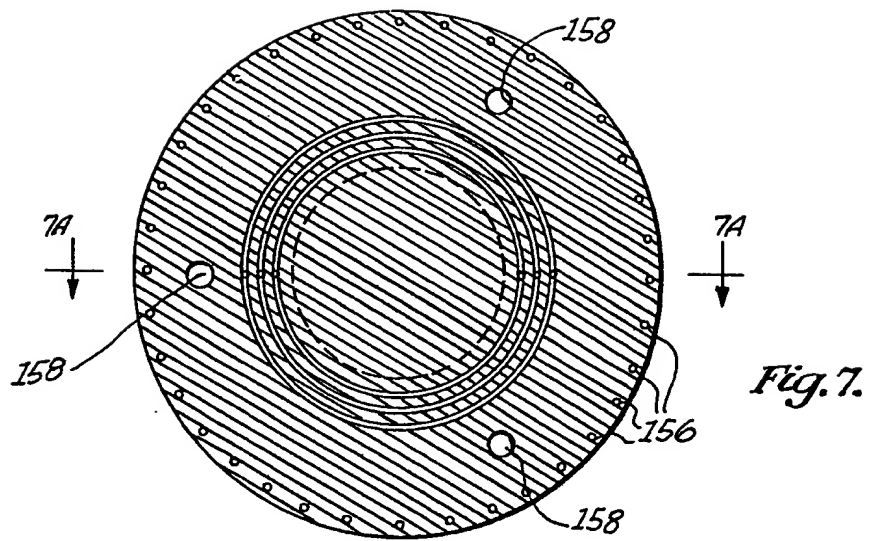


Fig. 6.

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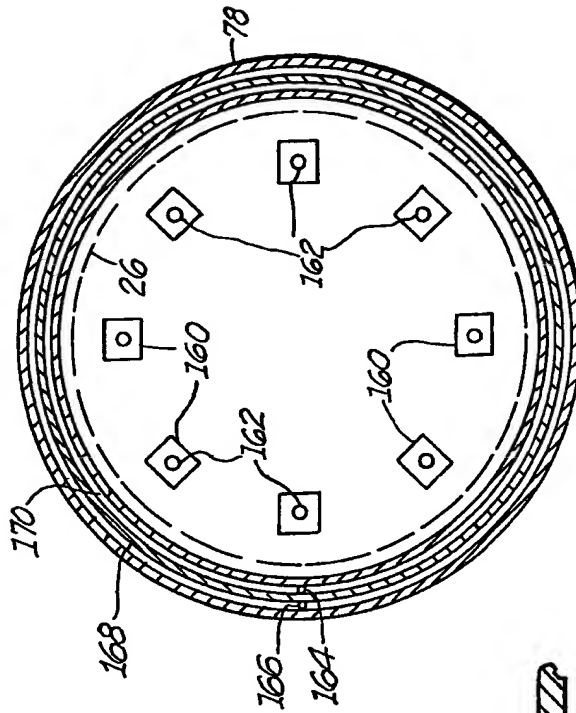


Fig. 9.

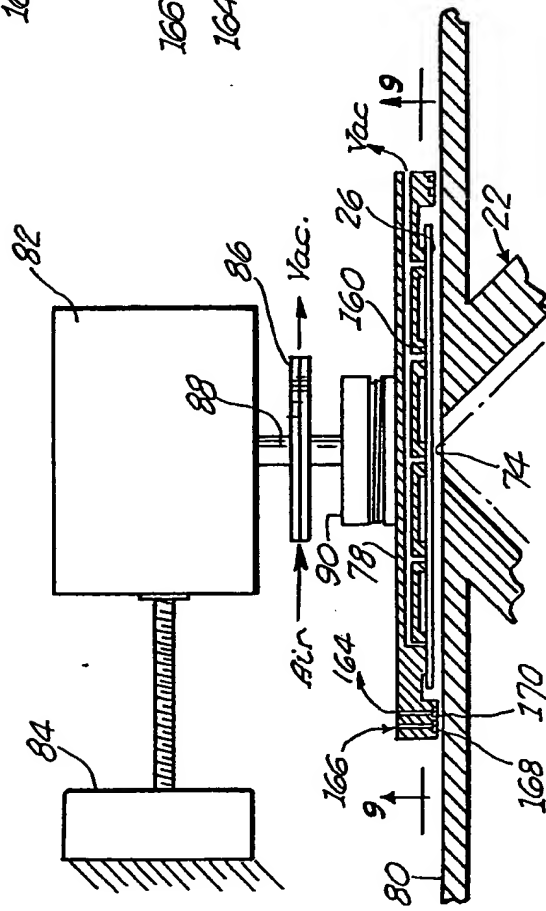


Fig. 8.

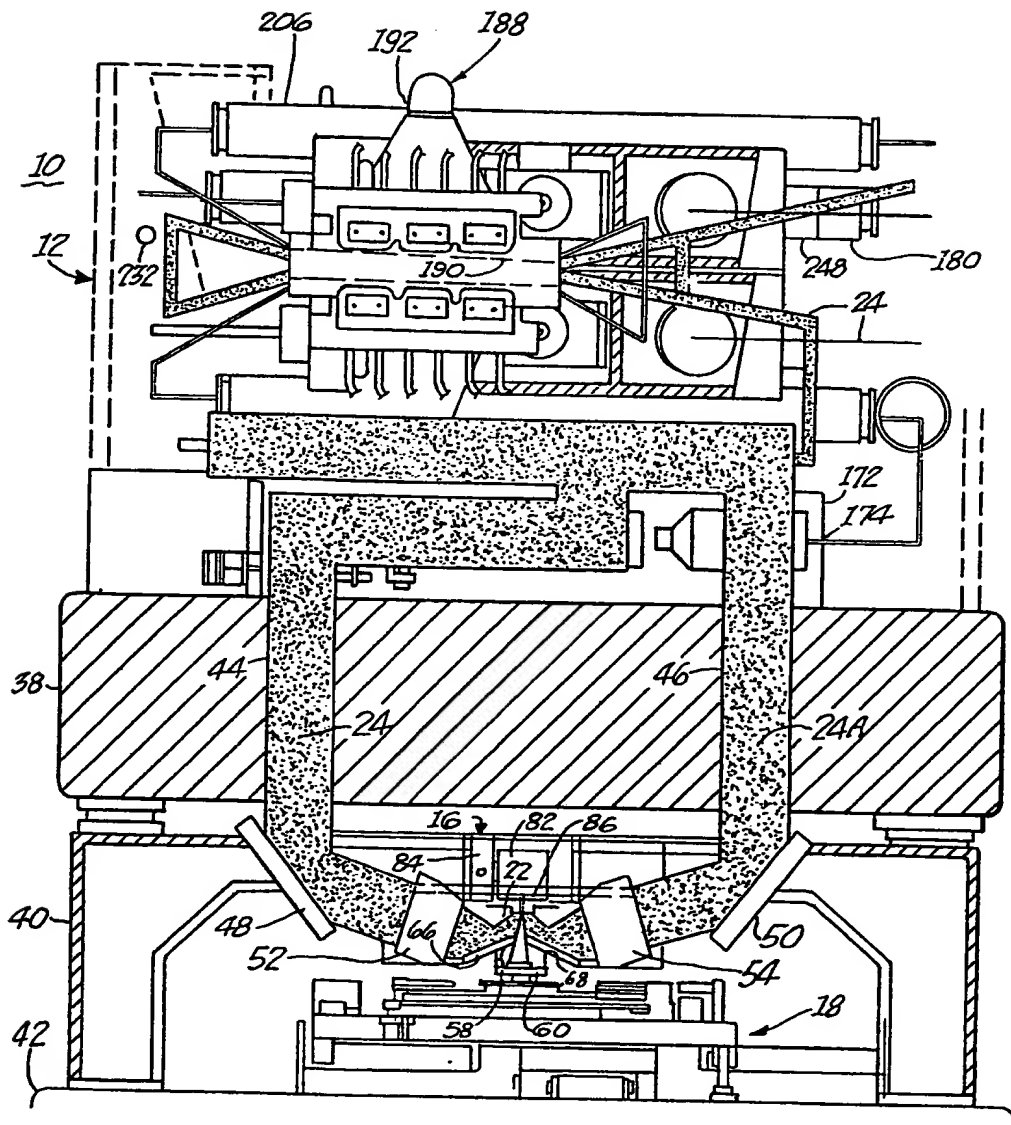
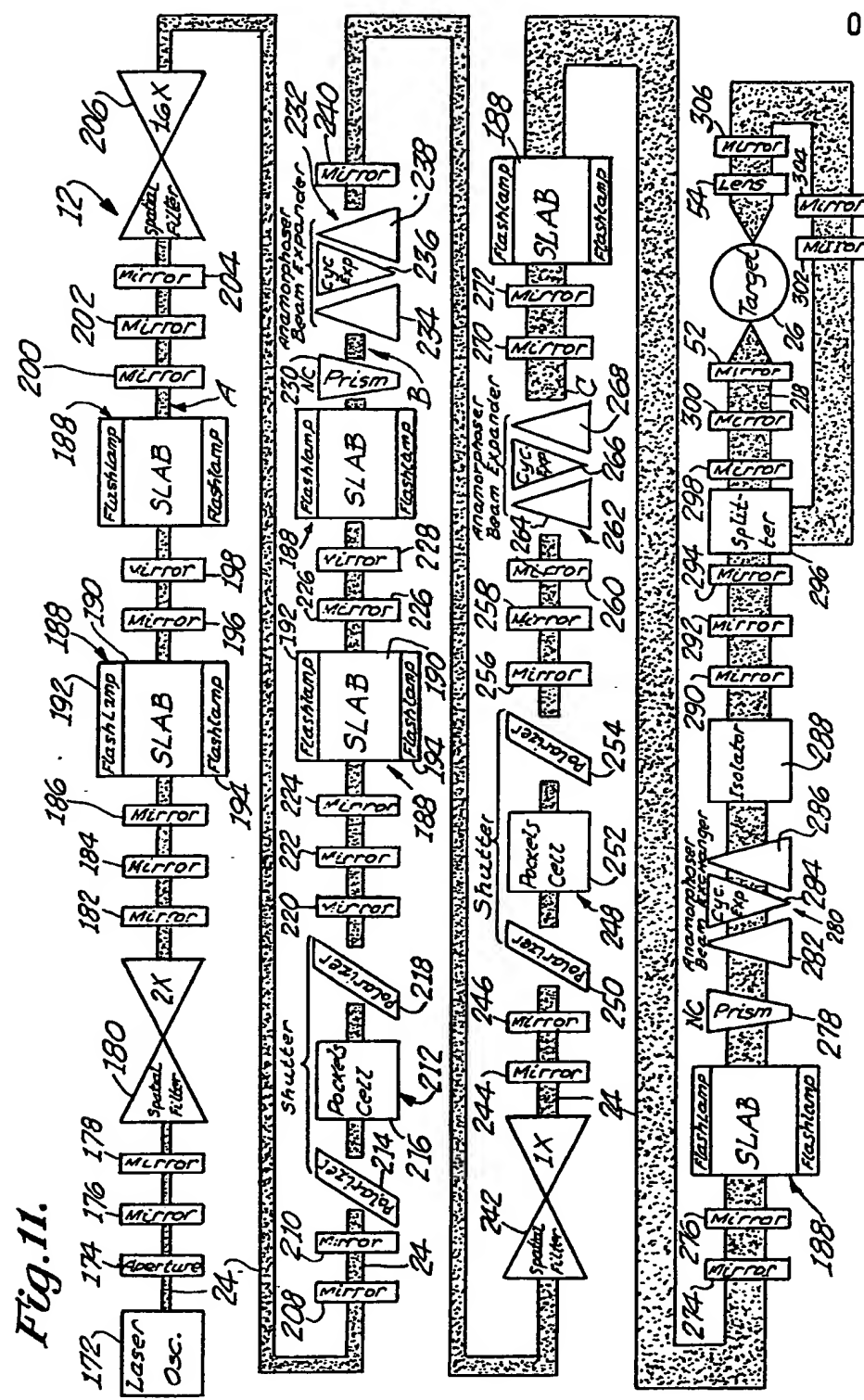
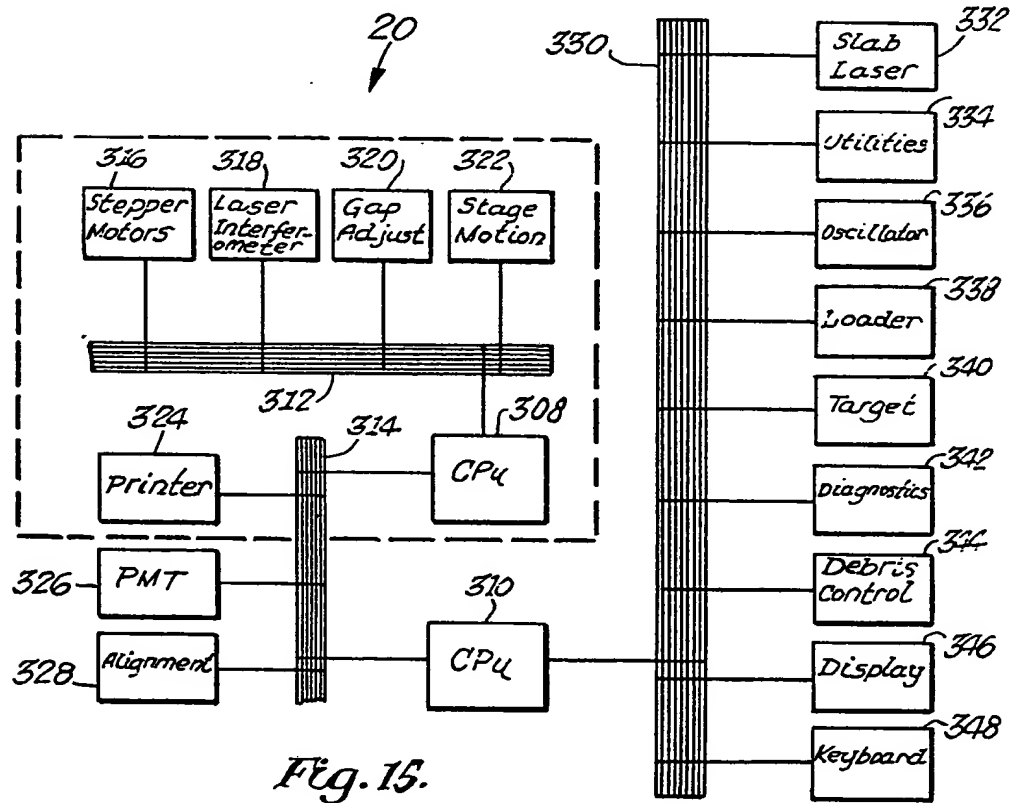
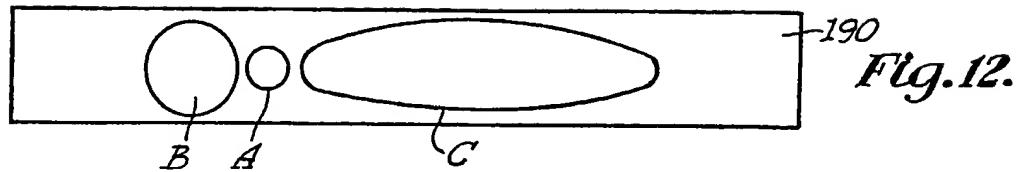
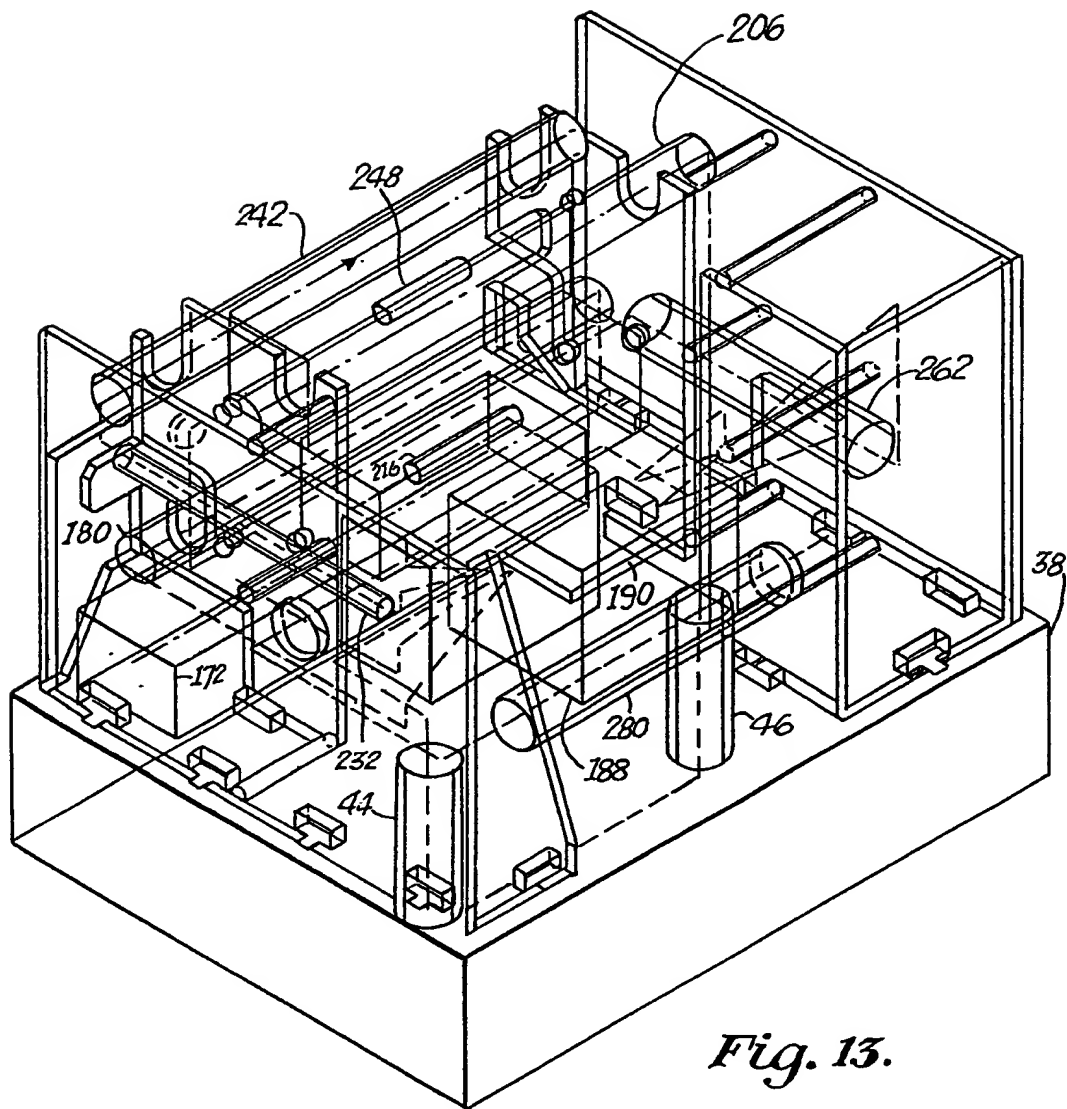


Fig. 10.

Fig. 11.







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Fig. 14A.

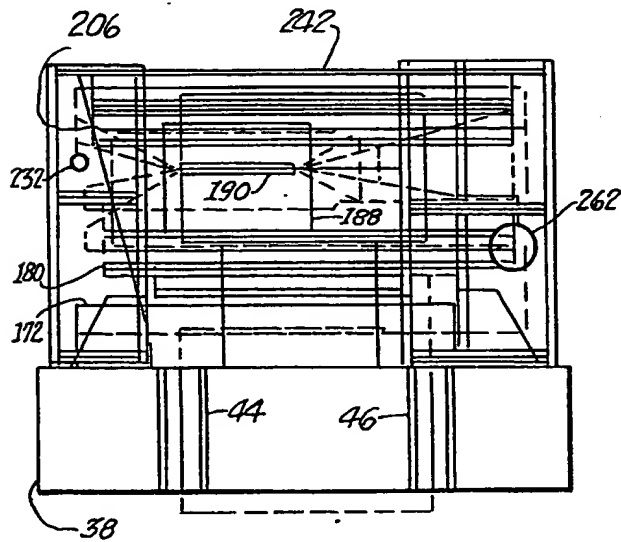
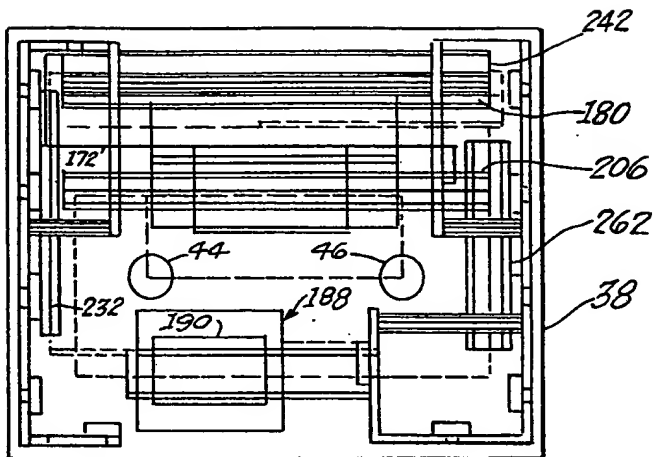


Fig. 14B.

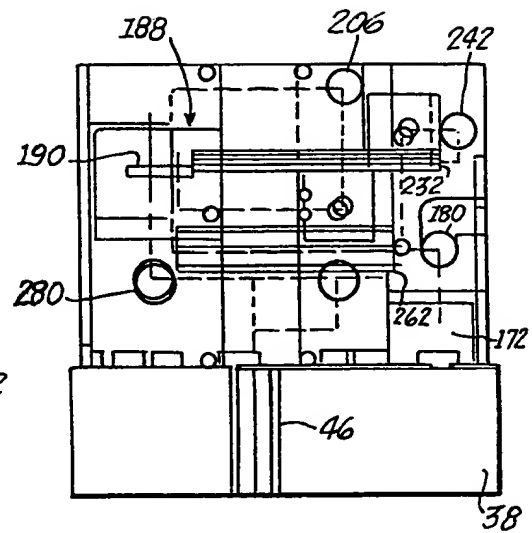


Fig. 14C.



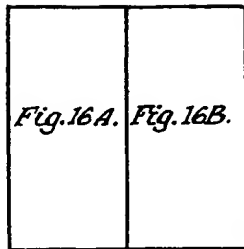


Fig. 16.

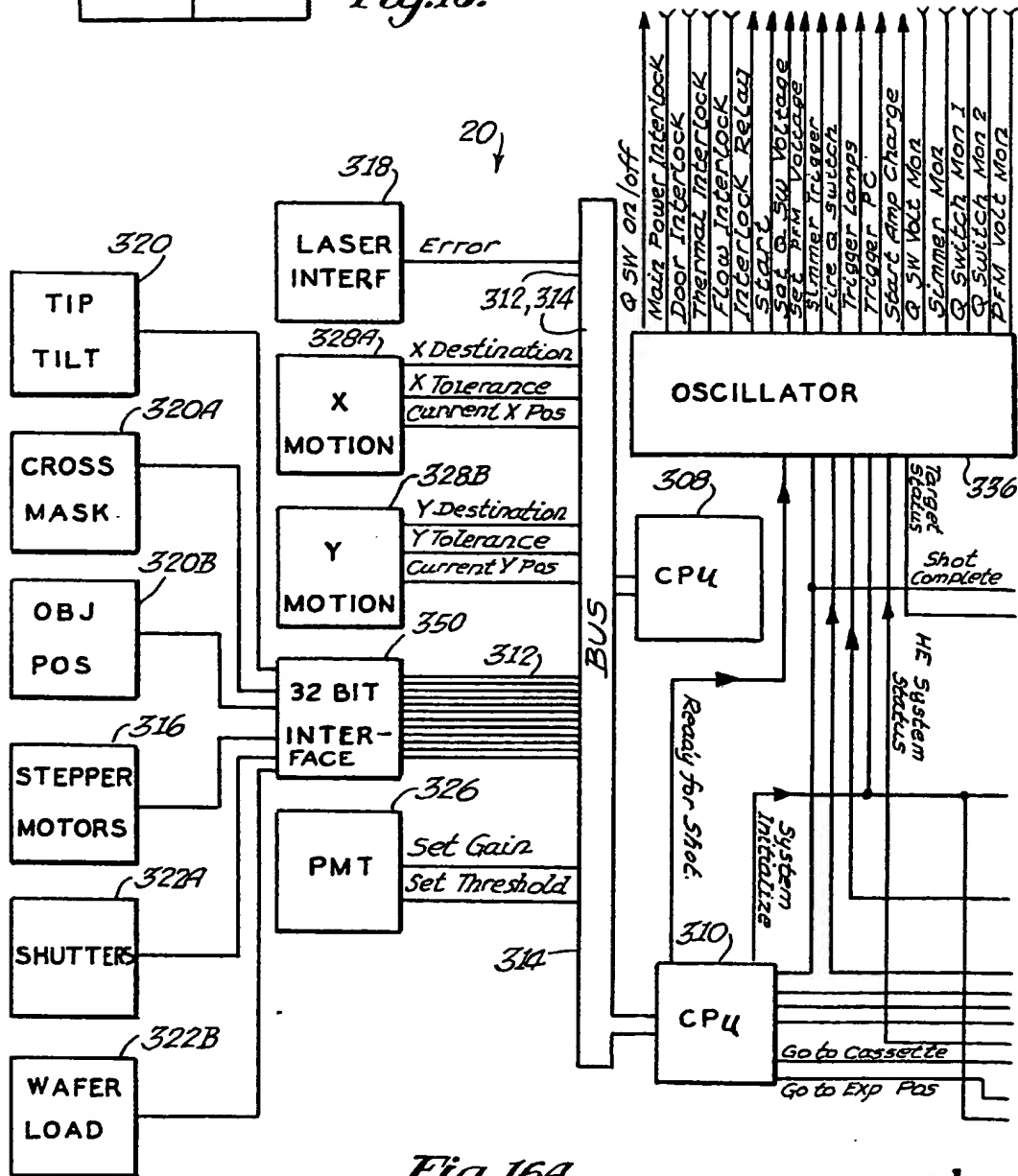


Fig. 16A.

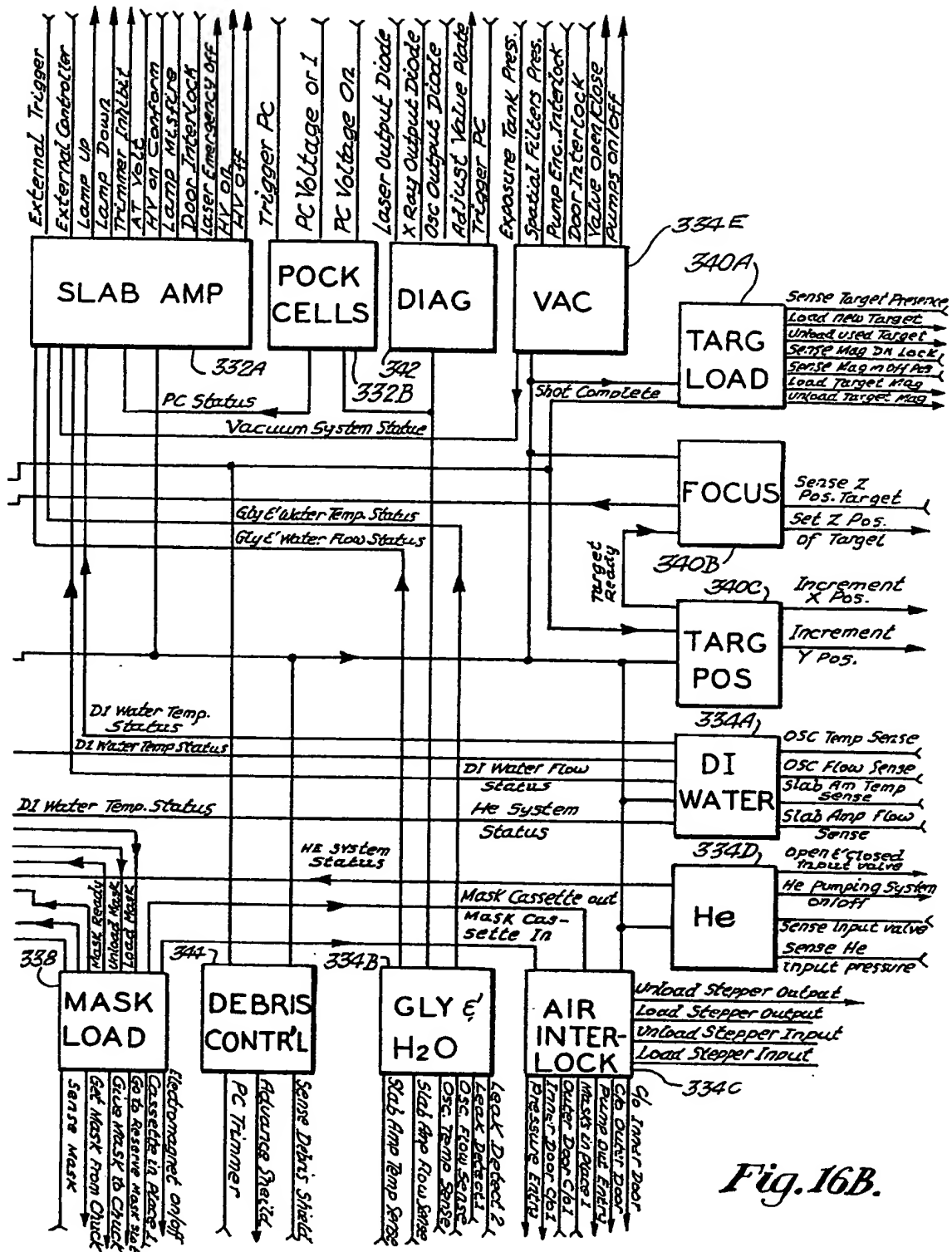


Fig. 16B.

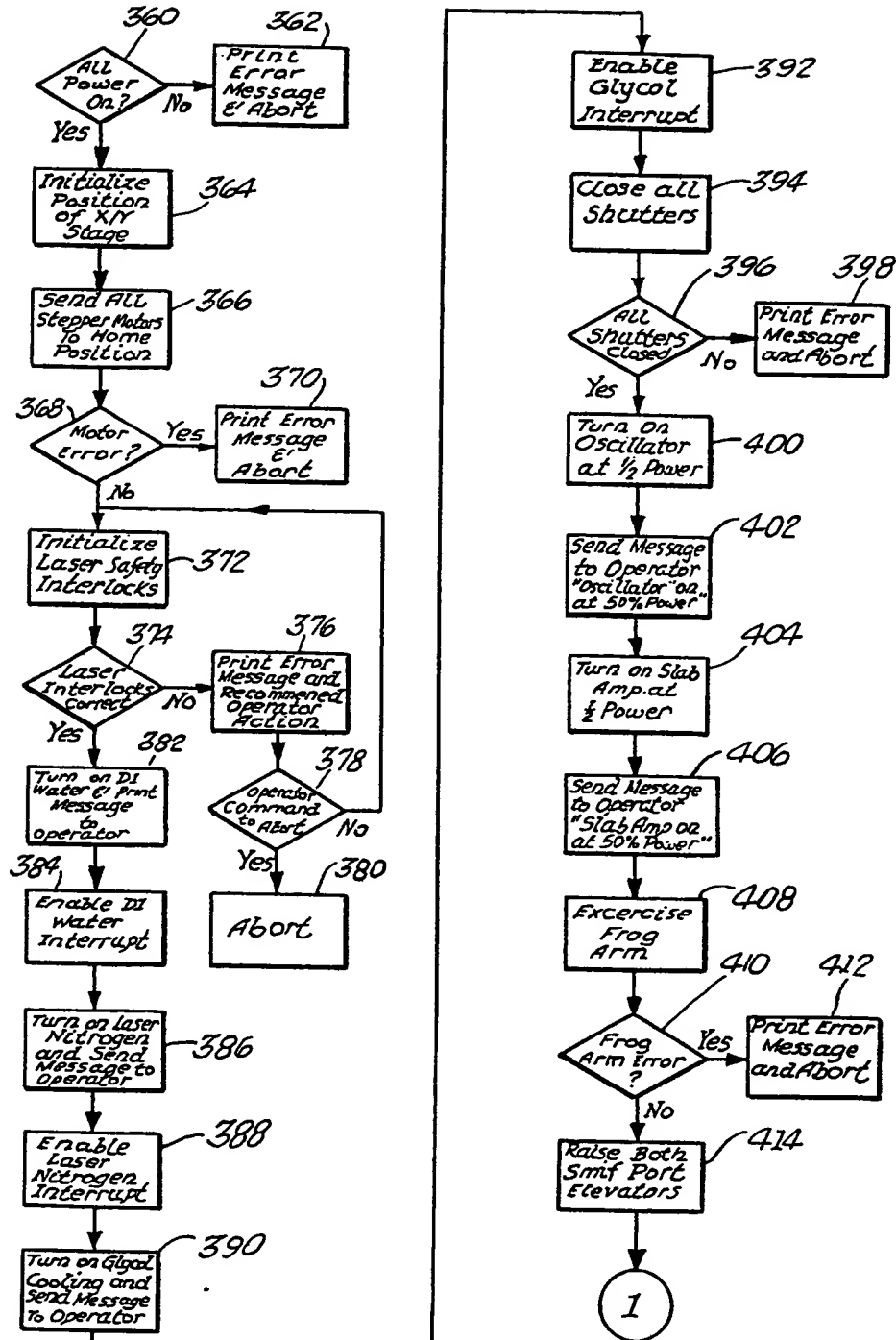


Fig. 17A.

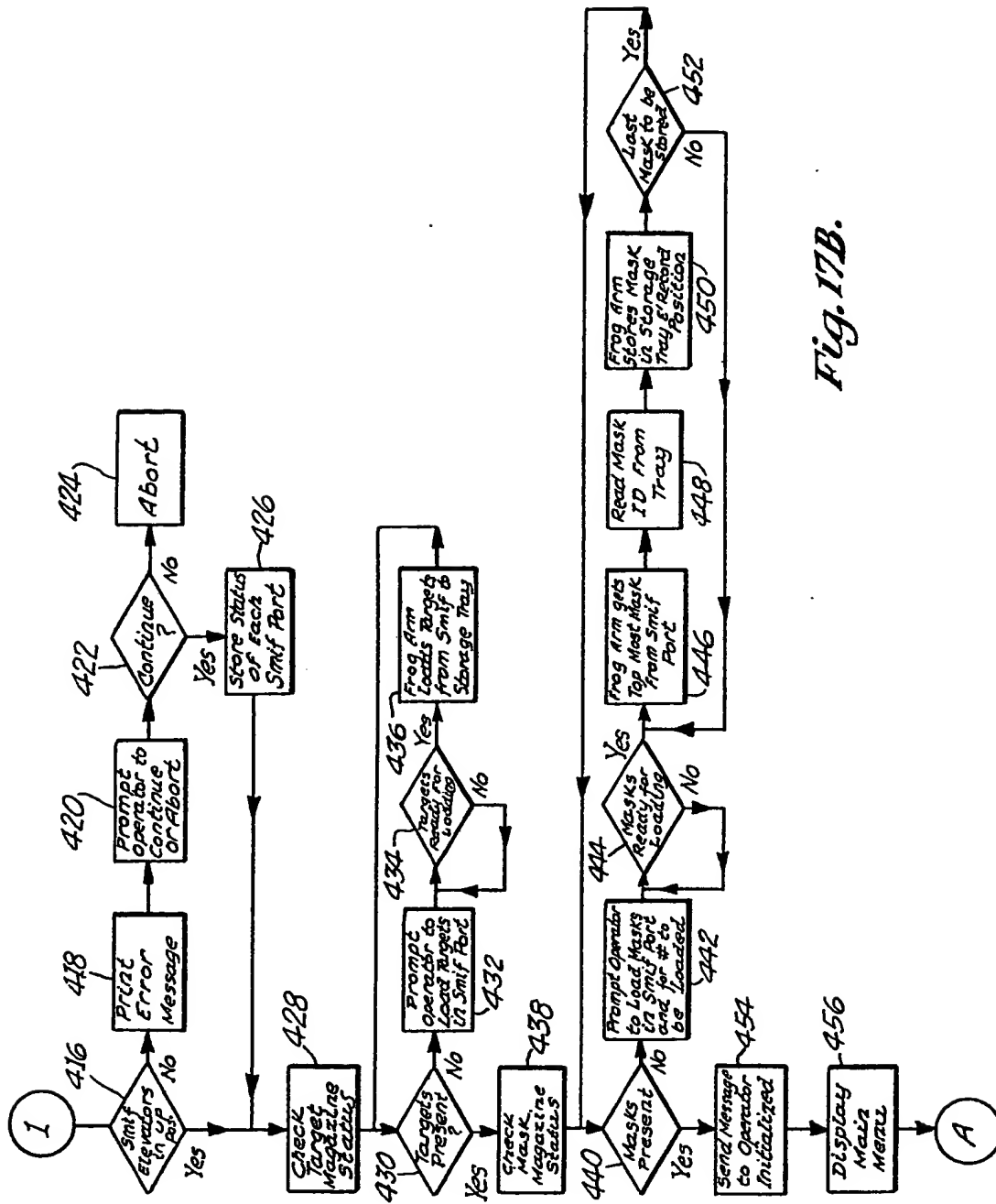
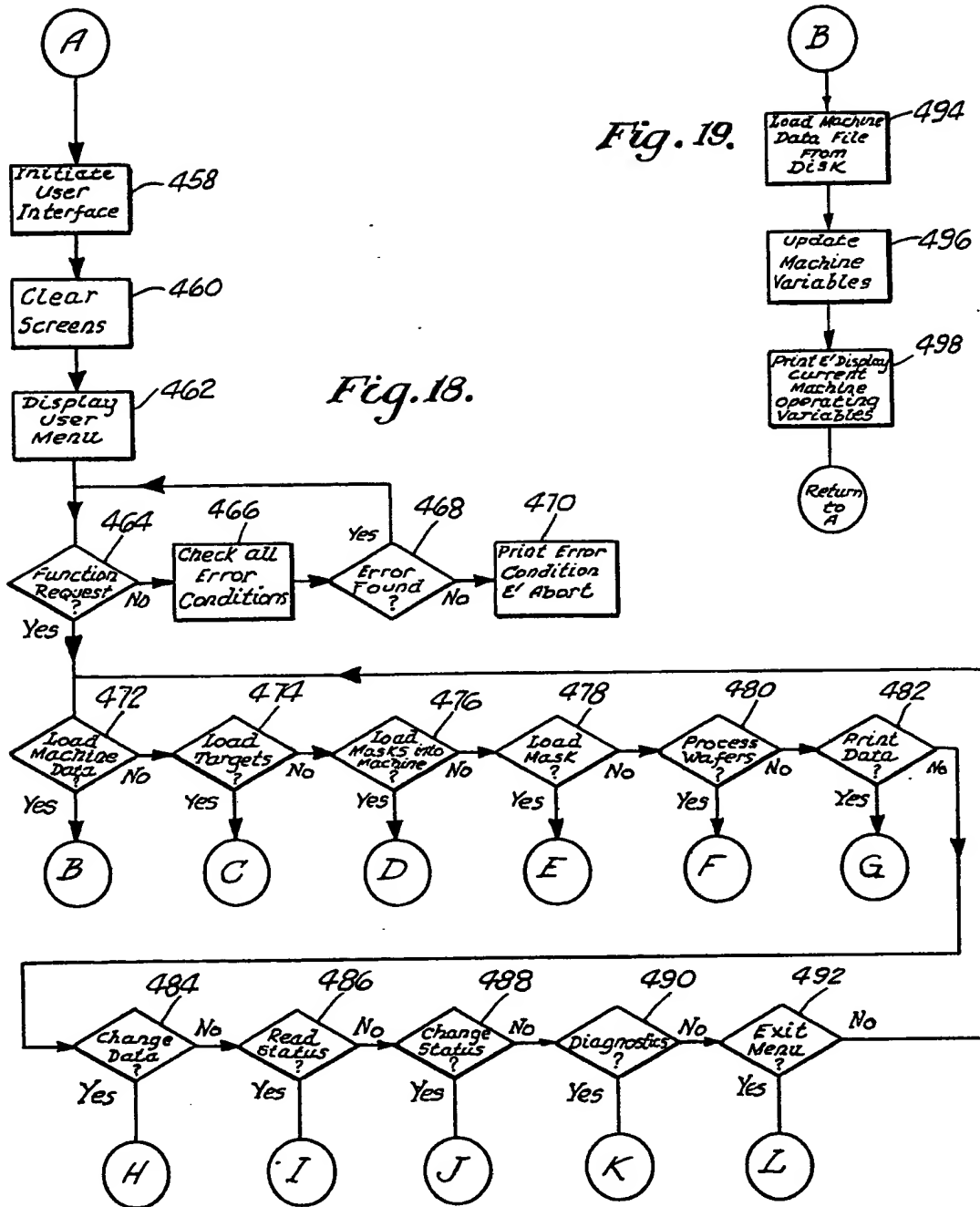
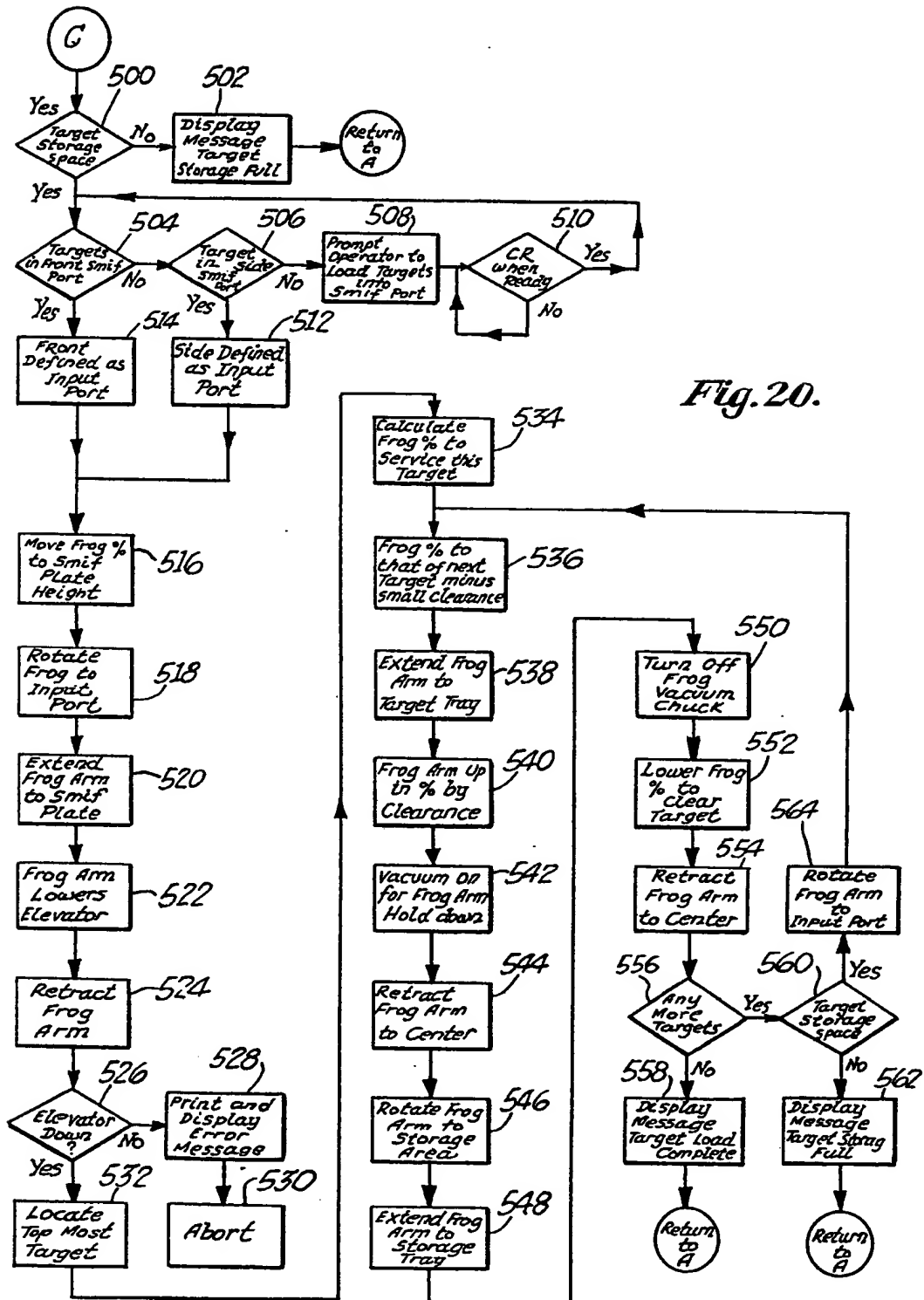


Fig. 17B.





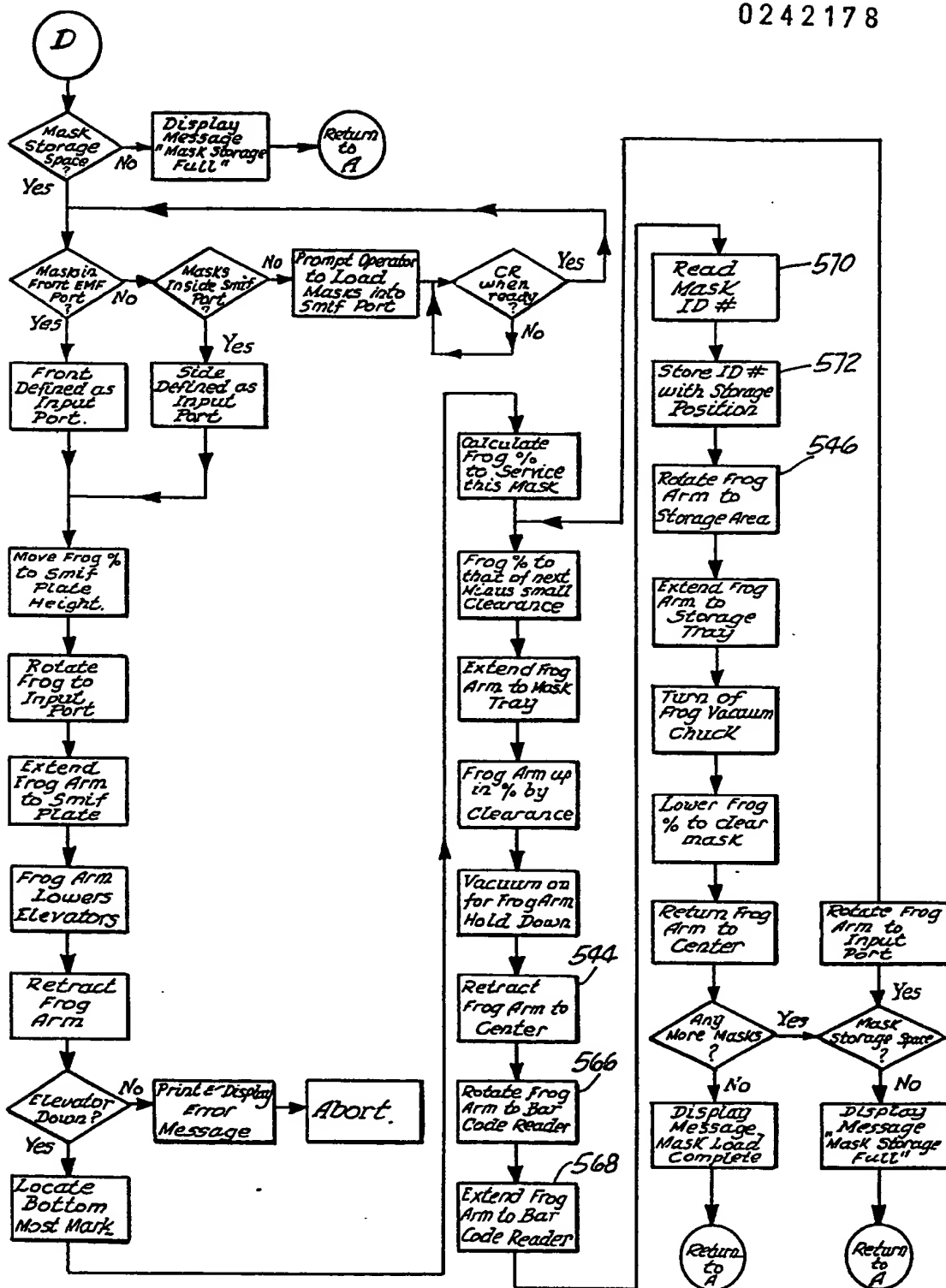


Fig. 21.